

Measuring the dynamics of gels

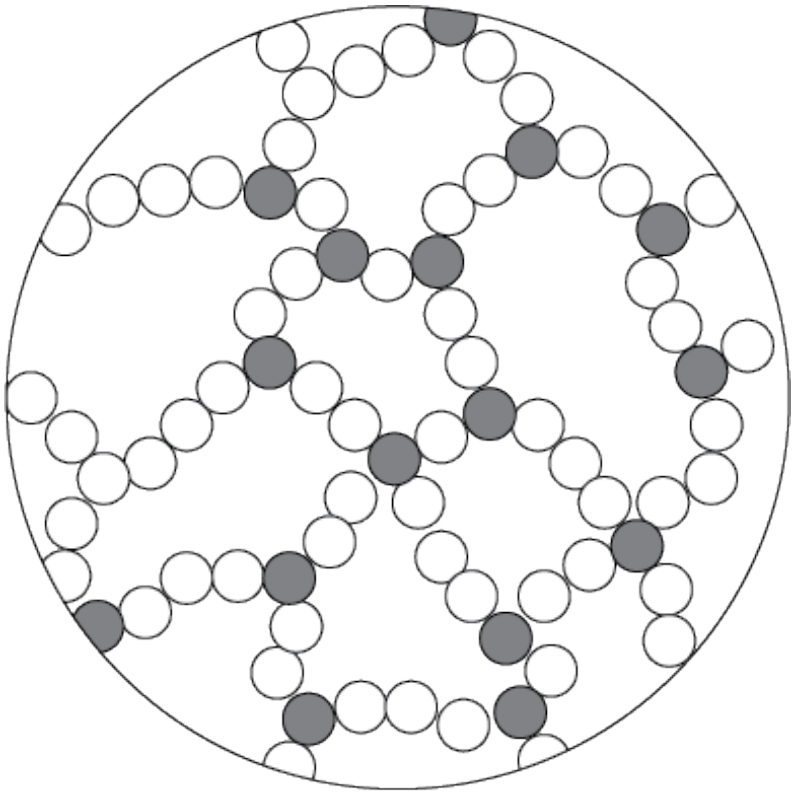
Jake Song

Department of Materials Science and Engineering
Program for Polymer and Soft Matter

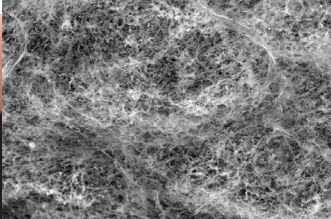
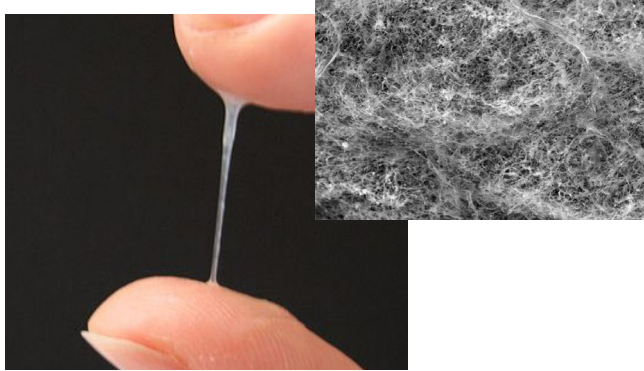


Massachusetts Institute of Technology

Gels



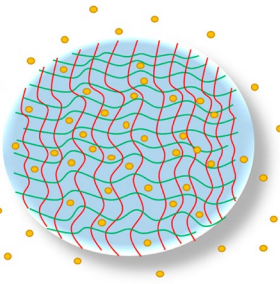
Constituent material (polymer)
Swollen in solvent (water -> "hydrogel")
Bound and forms a network through cross-links



Biological fluids
e.g. mucus, biofilm

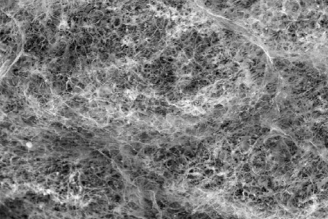
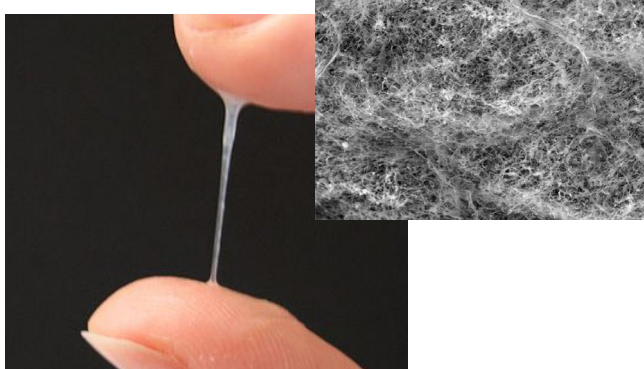
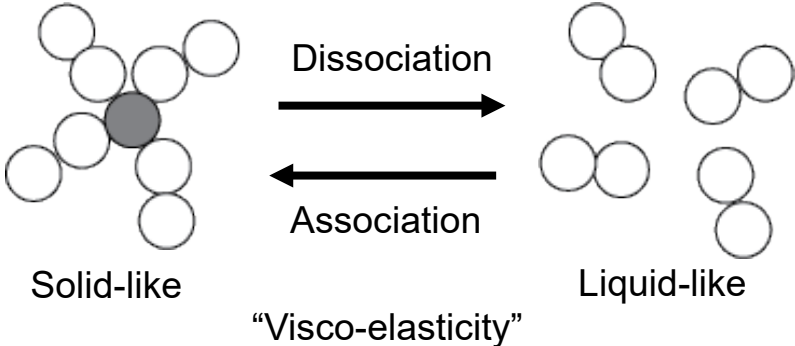
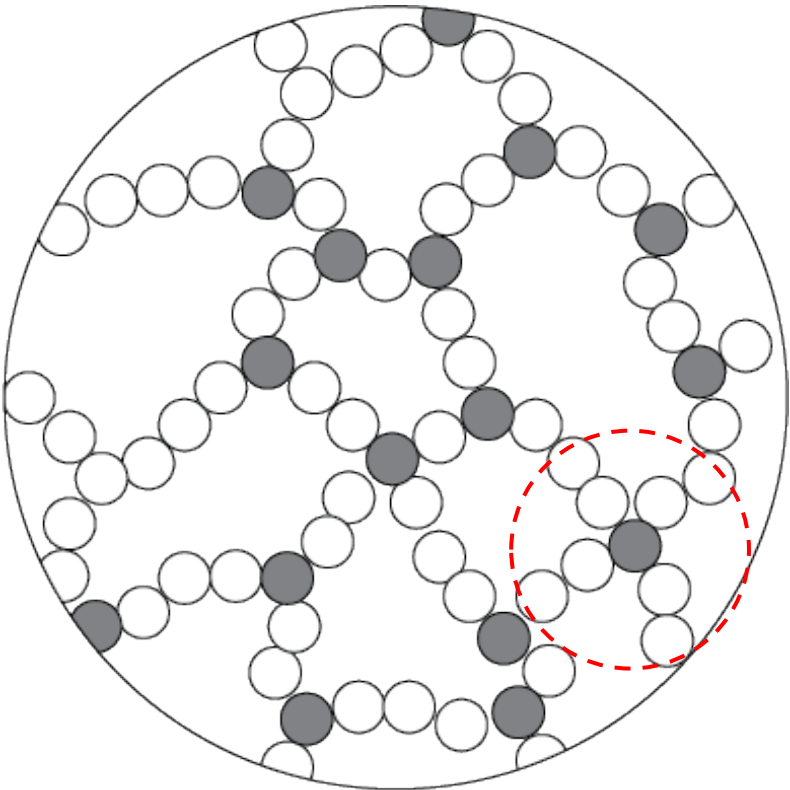


Biological materials
e.g. ECM, cells

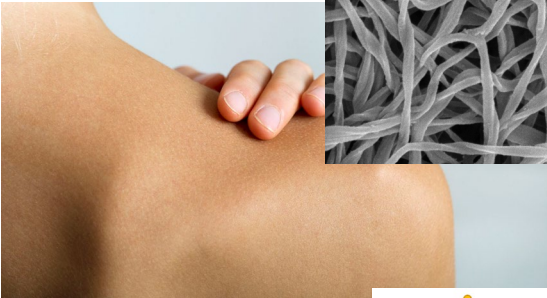


Biomaterials
e.g. drug carriers, implants

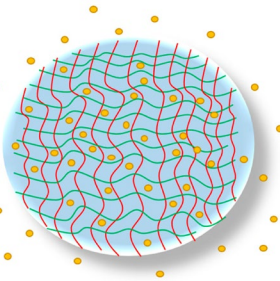
Gels



Biological fluids
e.g. mucus, biofilm



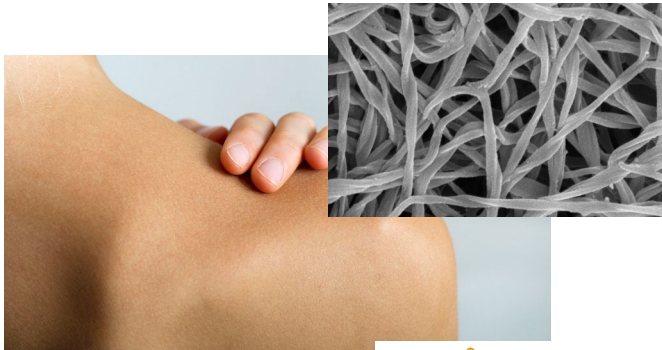
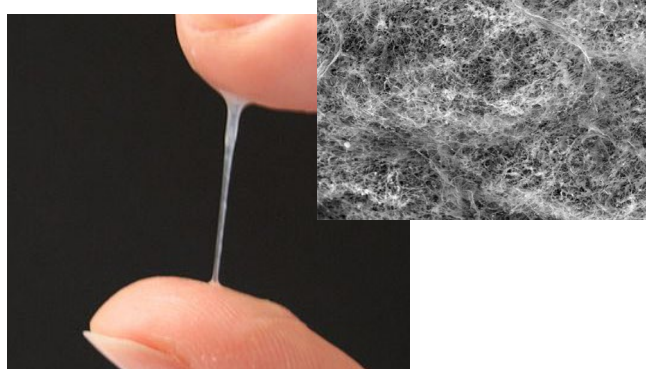
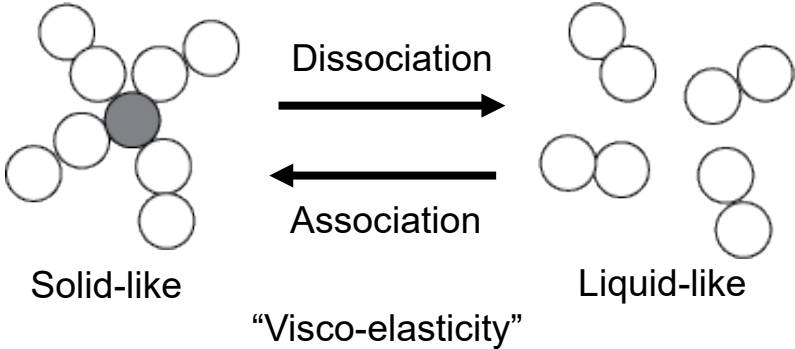
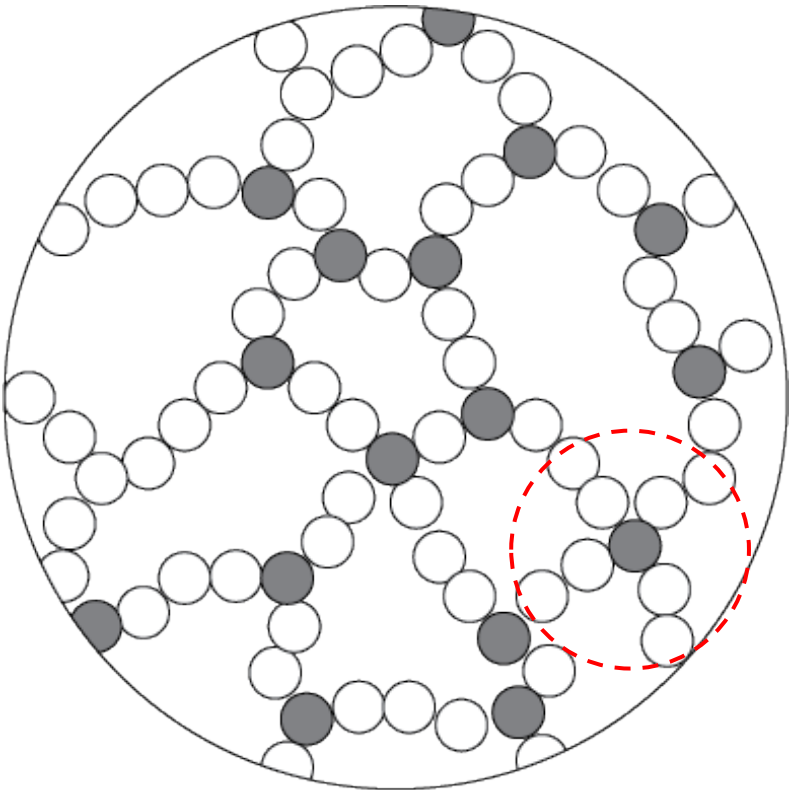
Biological materials
e.g. ECM, cells



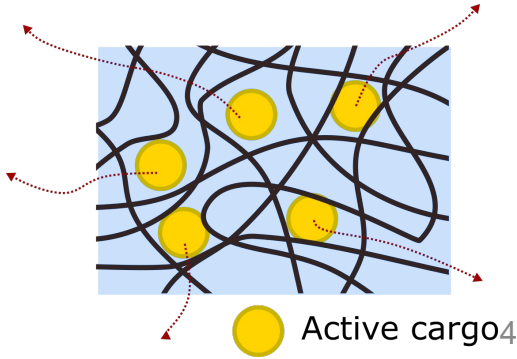
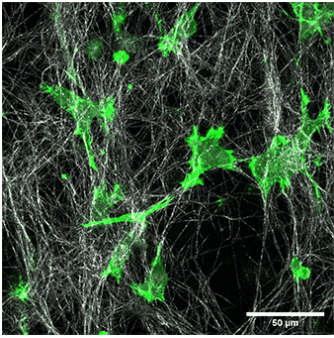
Biomaterials
e.g. drug carriers, implants

Gels

Dynamics and viscoelasticity dictate final properties of hydrogels

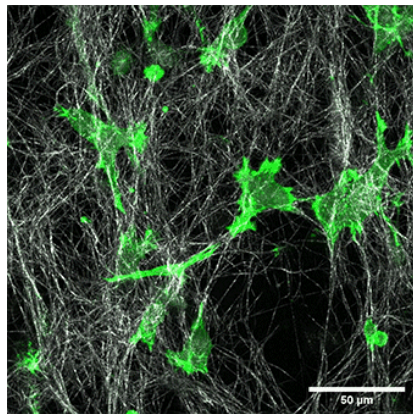
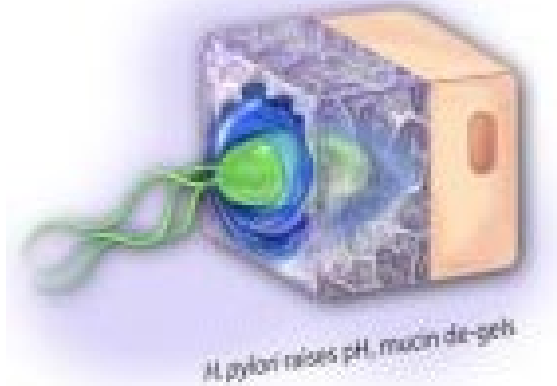


Bansil et al., PNAS 2009



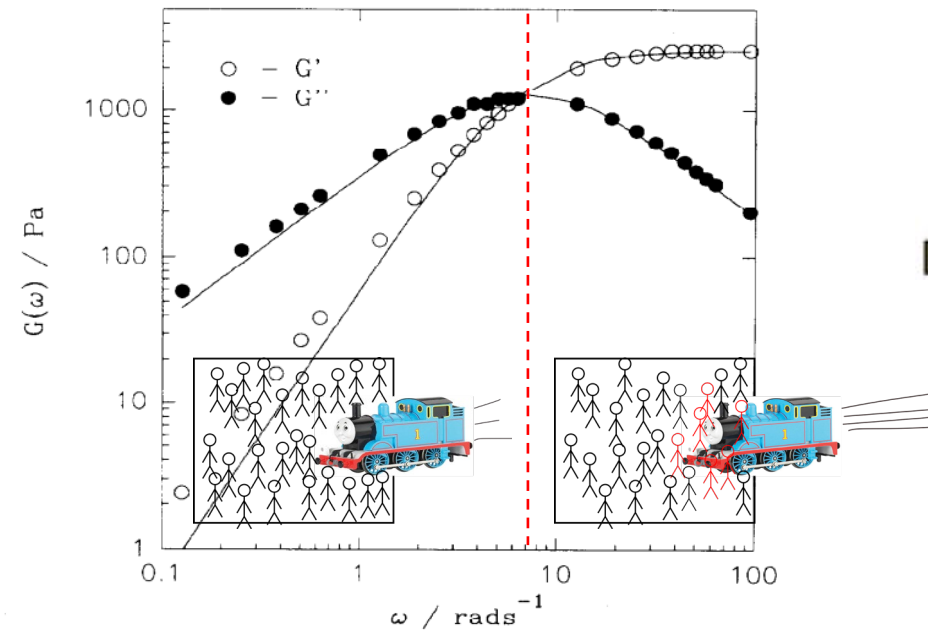
Viscoelasticity

Why should we care?
Dynamics affects crucial biological function

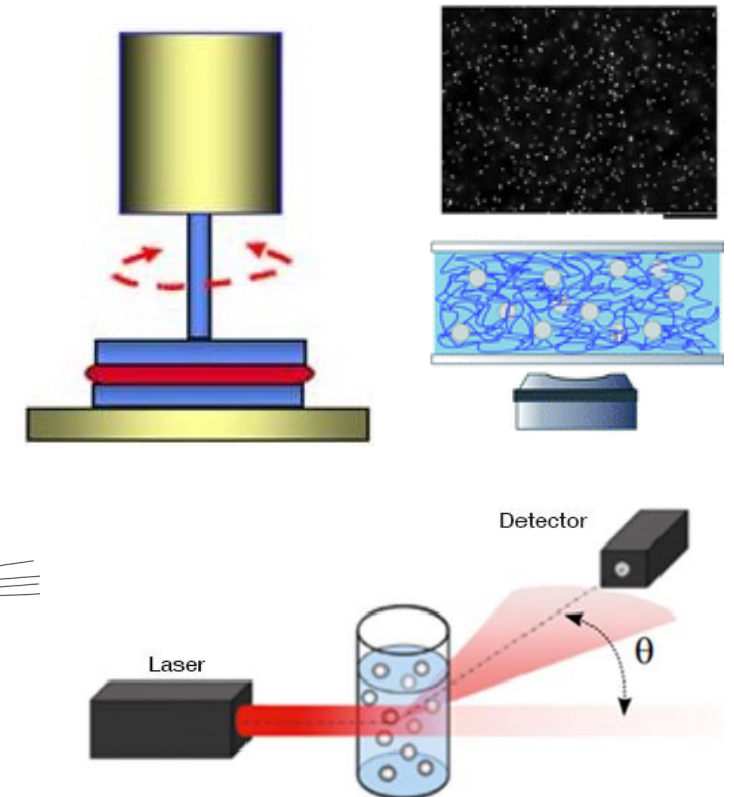


What is it?

Measure of elasticity, viscosity, and the dynamical timescale of the system

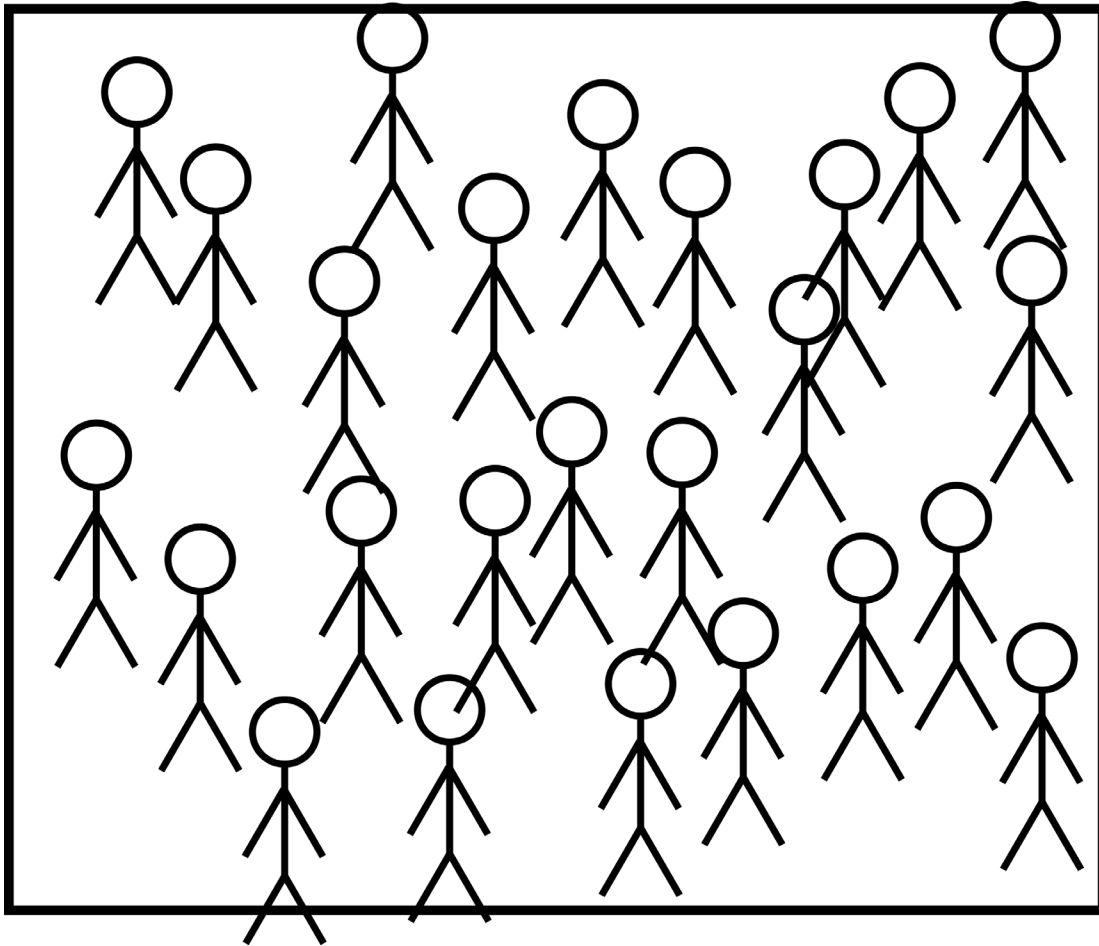


How do we measure it?
macrorheology, microrheology, ...

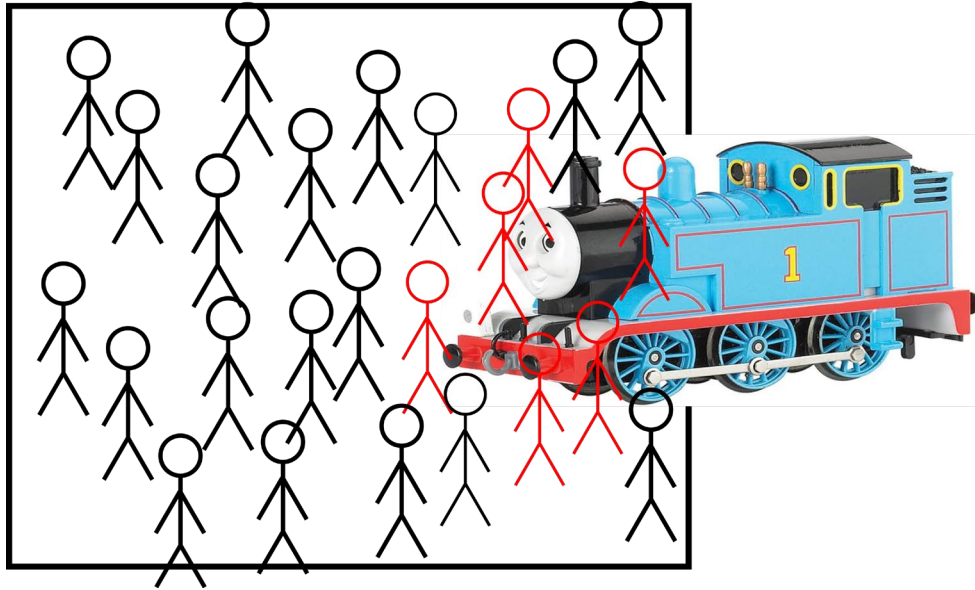


Viscoelasticity

The time/rate-dependent expression of viscosity and elasticity; ubiquitous in soft materials

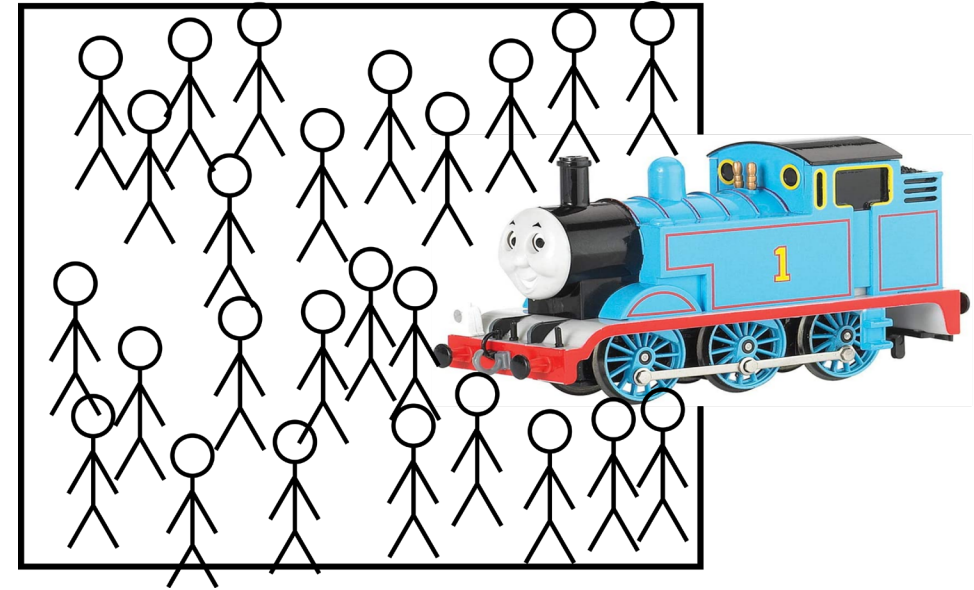


Viscoelasticity – rate dependence



High strain rate

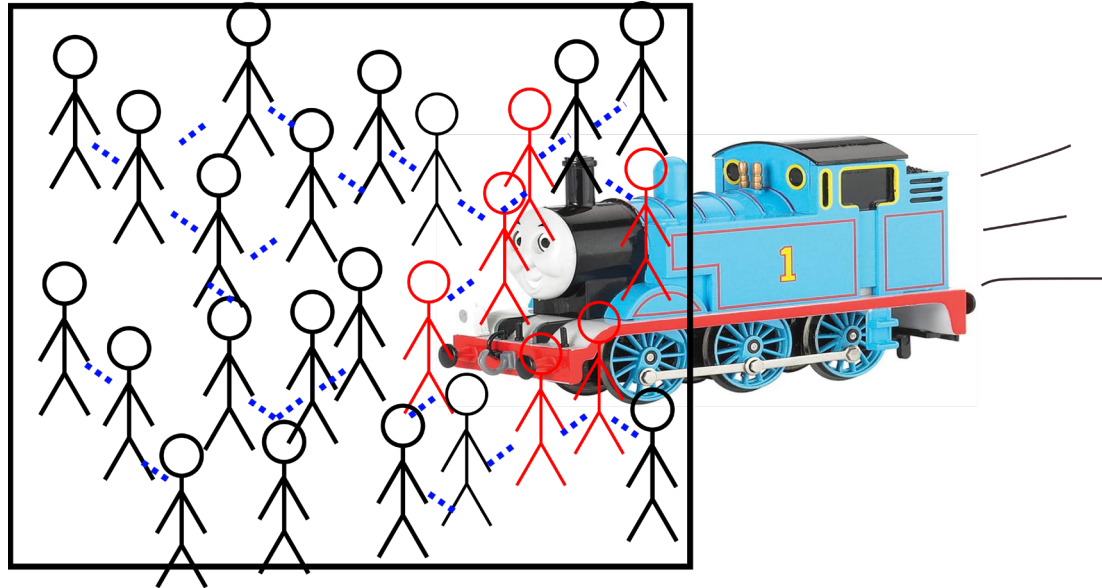
Insufficient time to rearrange
Solid-like “elastic” response



Low strain rate

Sufficient time to rearrange
No solid-like “elastic” response
Liquid-like “viscous” response

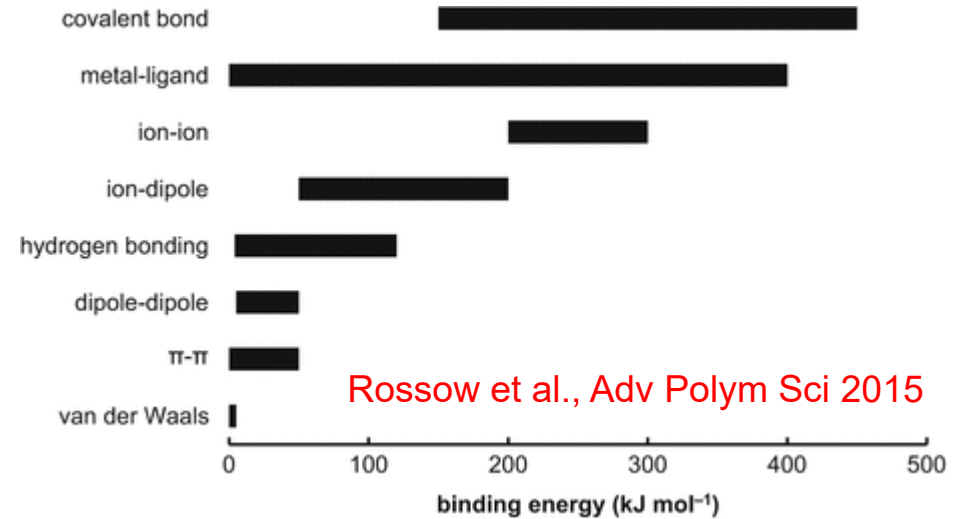
Viscoelasticity – rate dependence



Low strain rate, but with tethers

Rearrangement prevented by temporary bonds, such that slow strain rate can still elicit “elastic” response

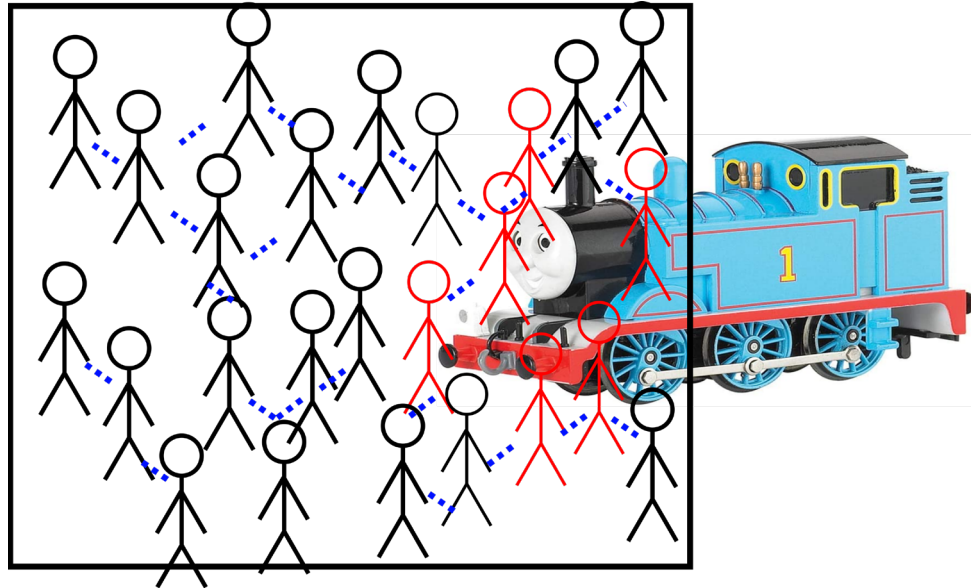
$$\text{Arrhenius equation: } \tau = \tau_0 \exp\left(-\frac{E}{kT}\right)$$



Bond lifetime controllable with different “physical bonds”, temperature, pH, ...

Interplay of strain rate and bond lifetime dictates solid-like response

Viscoelasticity – rate dependence



Weissenberg number

$Wi = \text{strain rate} \times \text{relaxation time}$
 $Wi = \dot{\gamma}\tau$

$Wi > 1$



Solid-like behavior

$Wi < 1$

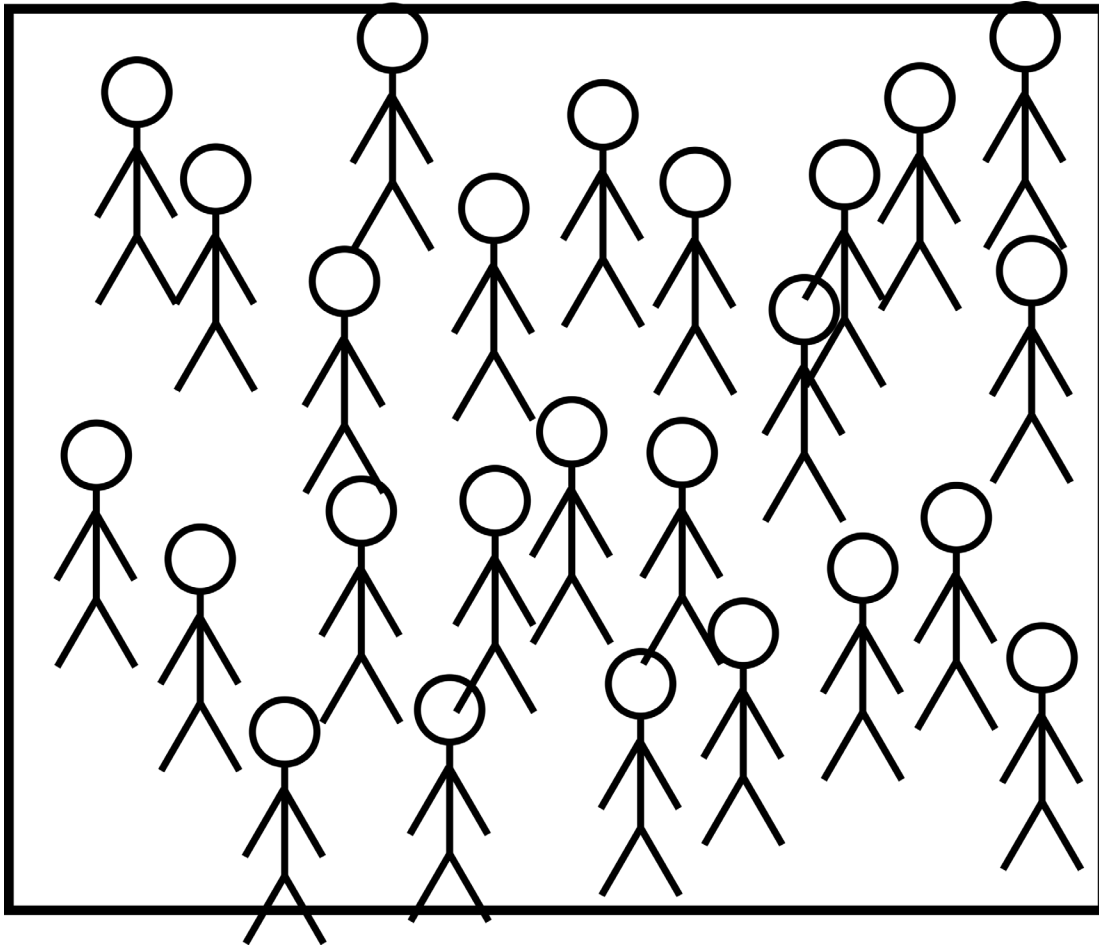


Liquid-like behavior

Low strain rate, but with tethers
Rearrangement prevented by temporary bonds, such that slow strain rate can still elicit “elastic” response

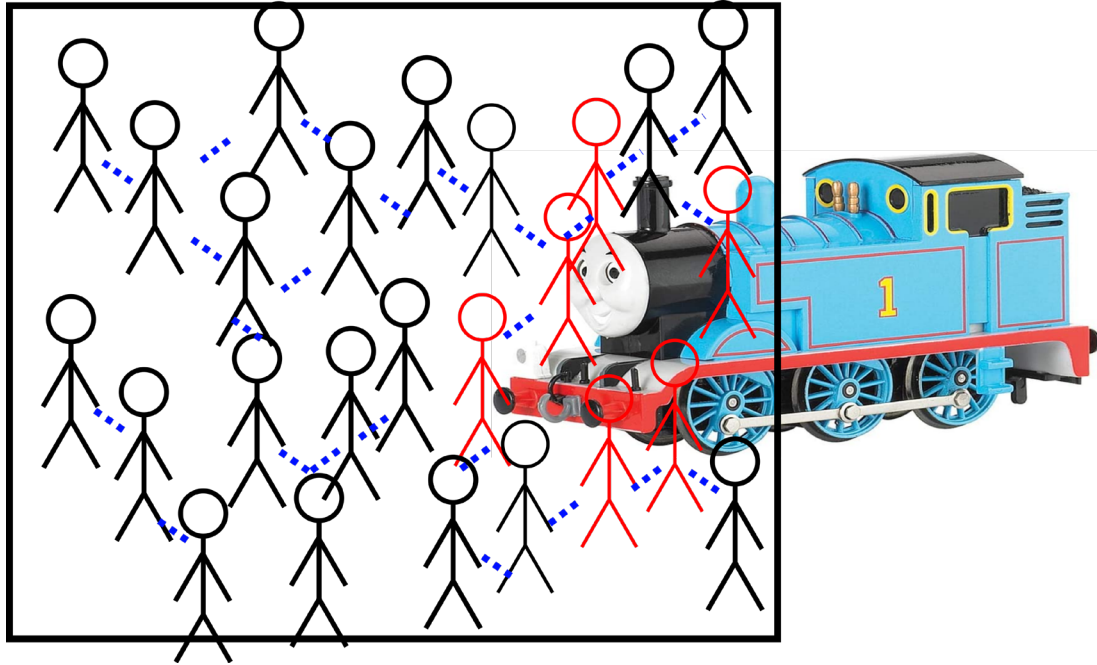
Probed by oscillatory shear measurements

Viscoelasticity

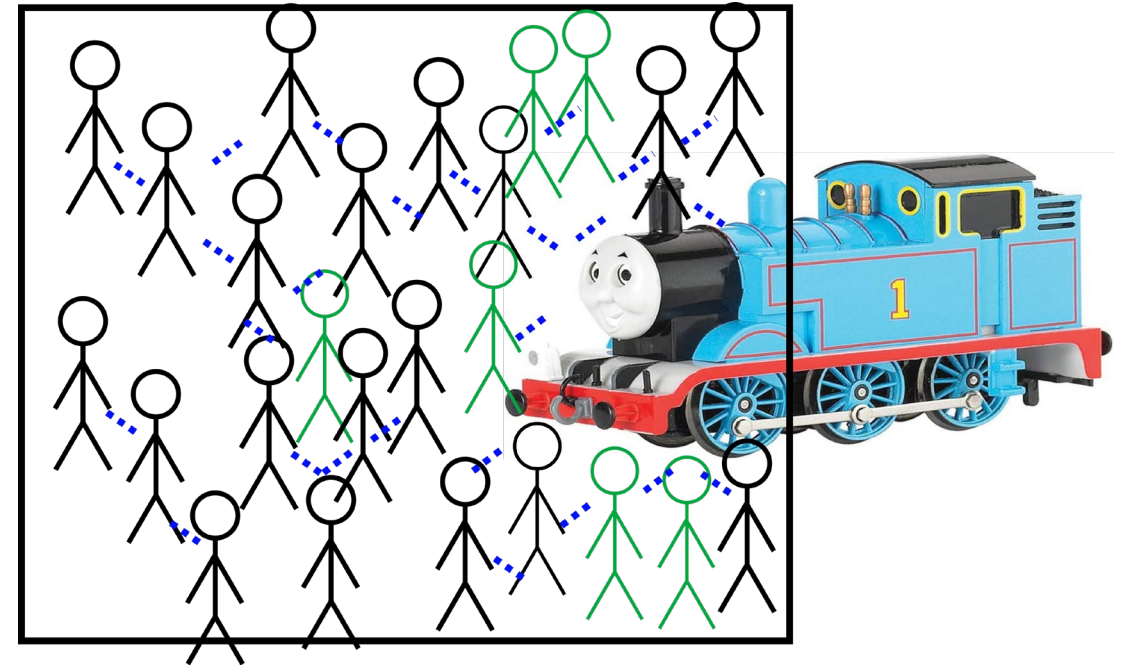


Crash and then park the train in the room...

Viscoelasticity – time dependence



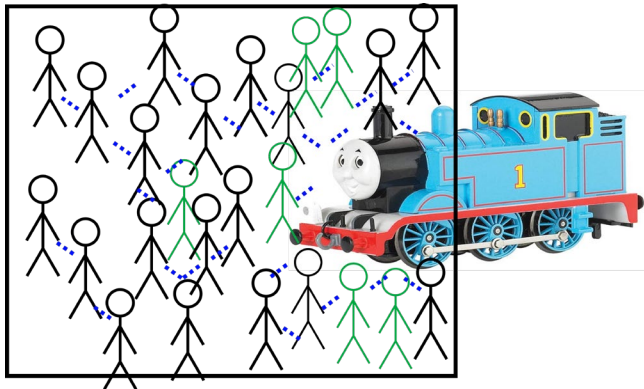
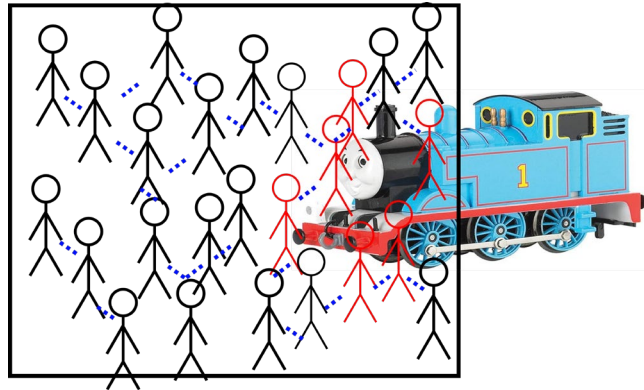
Short times after step deformation
“Elastic” response



Long times after step deformation
Enough time for rearrangements (at times longer than the “linker” lifetime)
Dissipation of the elastic response

Viscoelasticity – time dependence

time ↓



Probed by step strain measurements
“Stress relaxation”

Deborah number

$$De = \frac{\textit{relaxation time}}{\textit{observation time}}$$



$De > 1$

$De < 1$



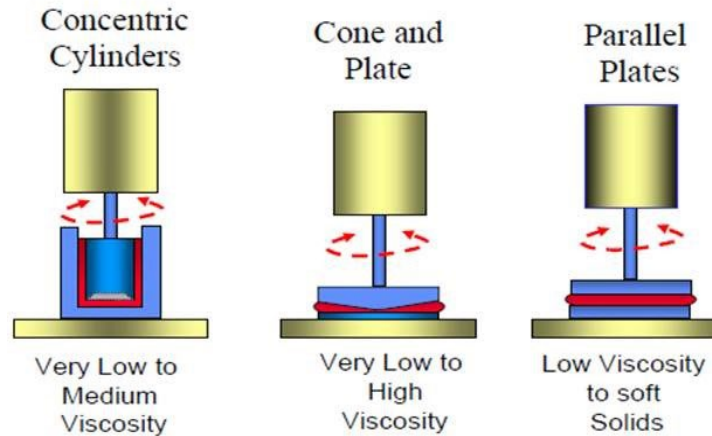
Solid-like behavior



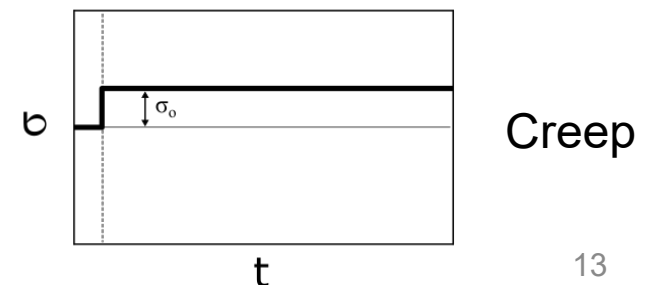
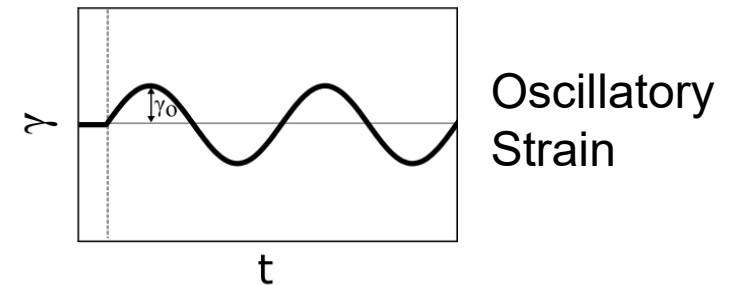
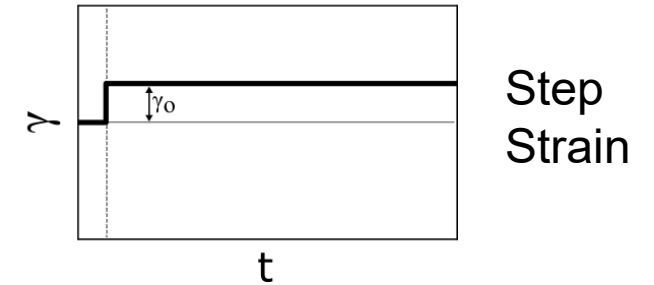
Liquid-like behavior

Rheology to study viscoelasticity

The most conventional approach: Use a rheometer

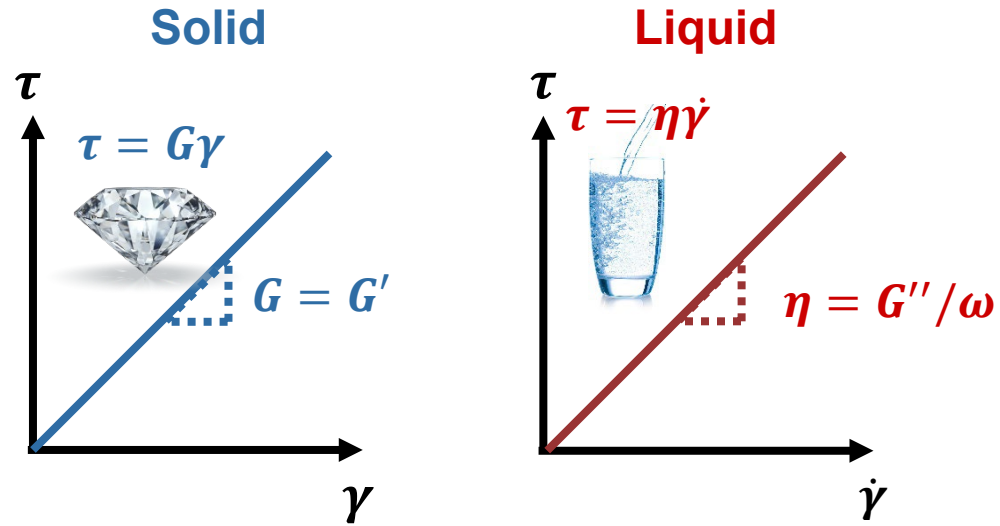


Typical sample volume:
 $60 \mu\text{L} \sim 1 \text{ mL}$

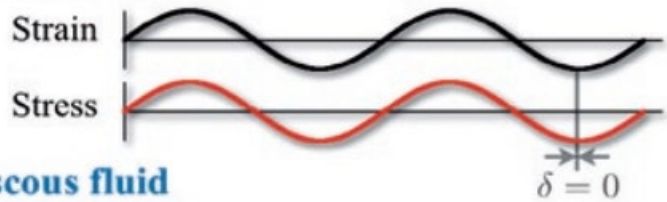


Useful textbook: "Rheology" by Chris Macosko

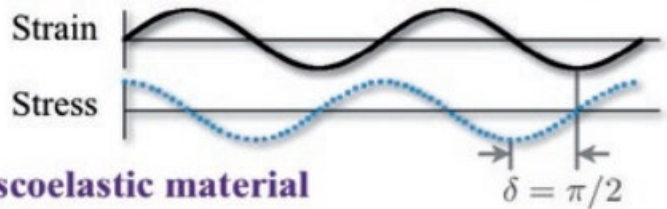
Rheology – Oscillatory Strain



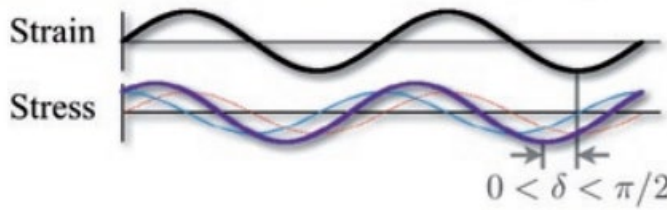
Elastic solid



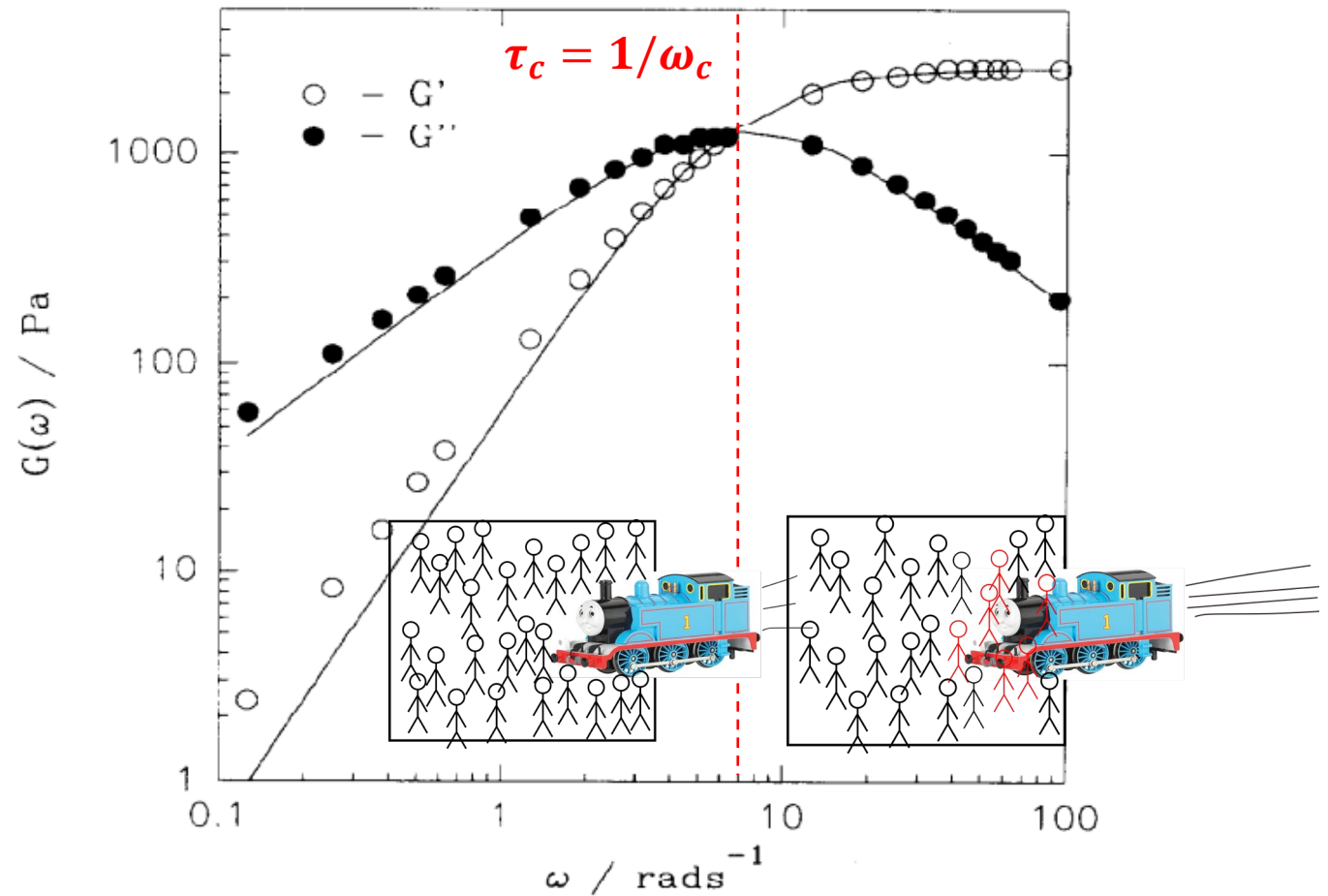
Viscous fluid



Viscoelastic material

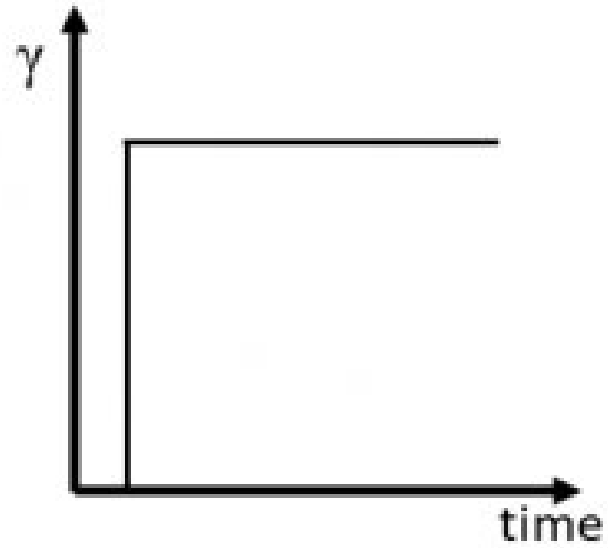


Example: Surfactant solution

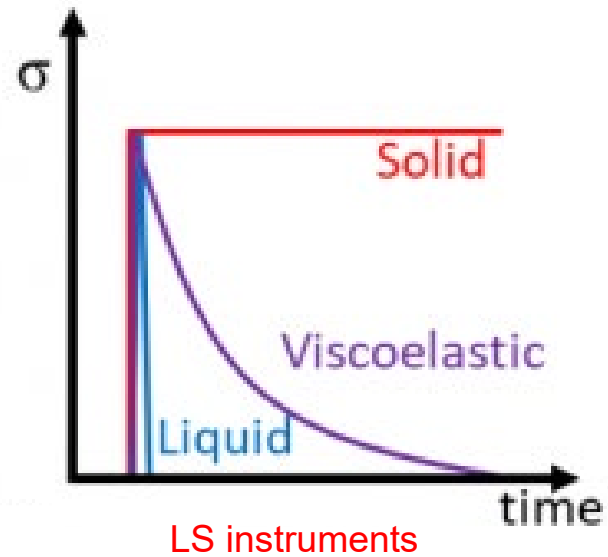


Rheology – Step Strain

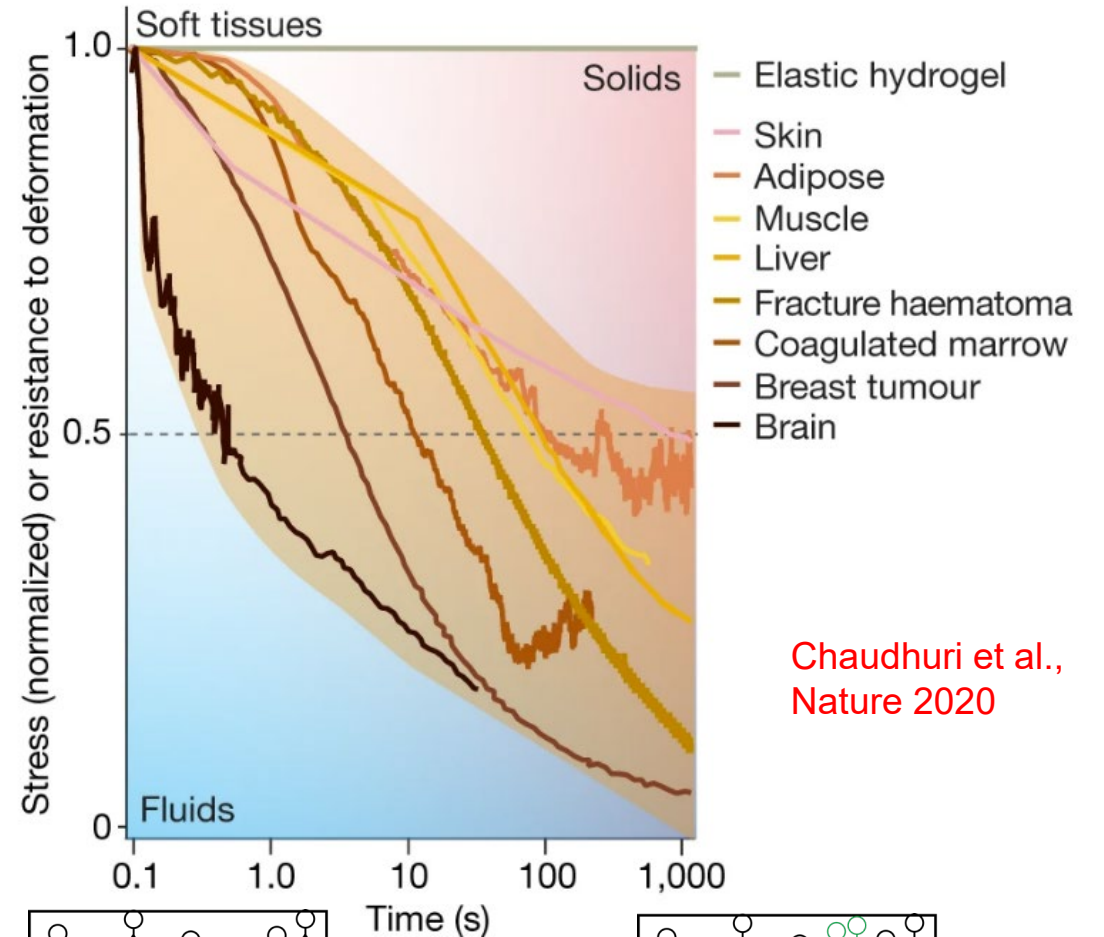
Impose step strain



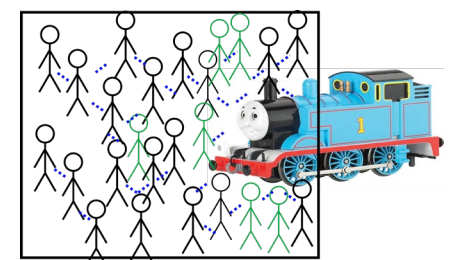
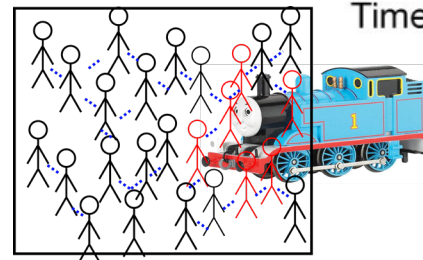
Observe time-dependent **stress relaxation**



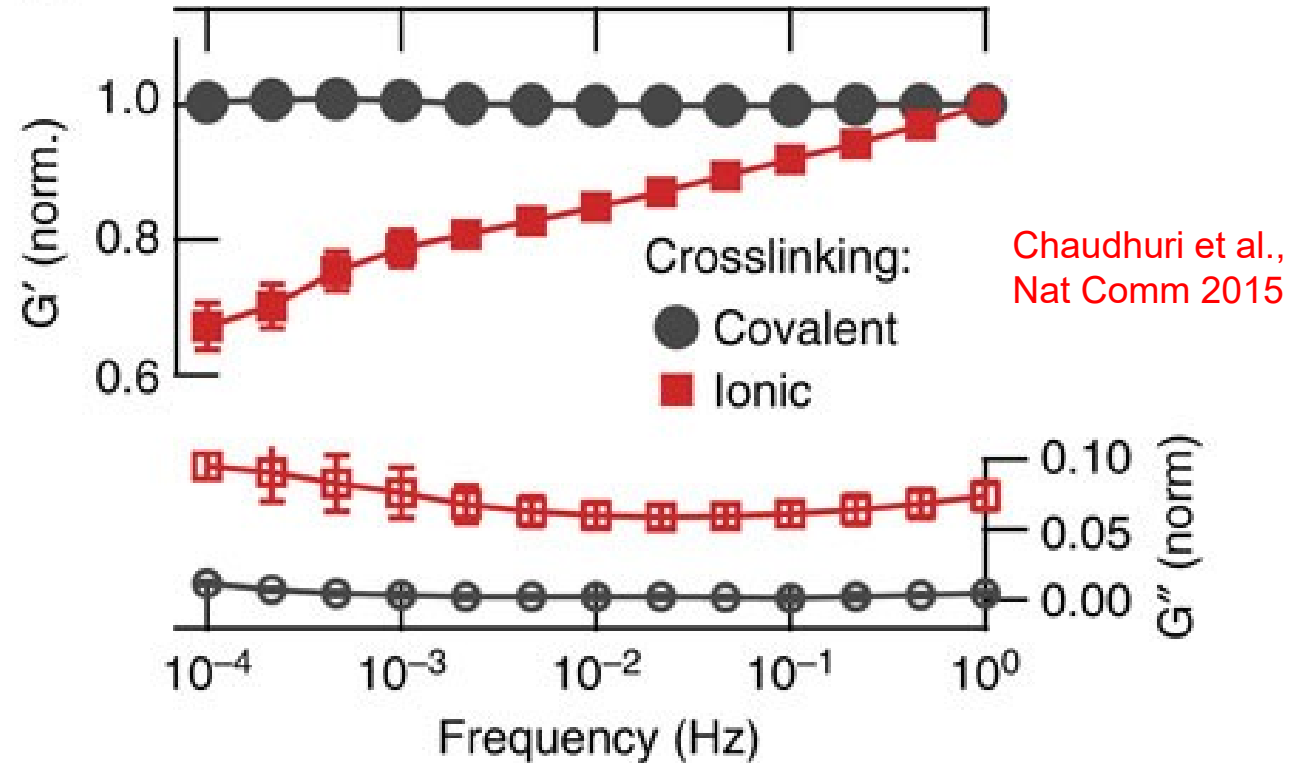
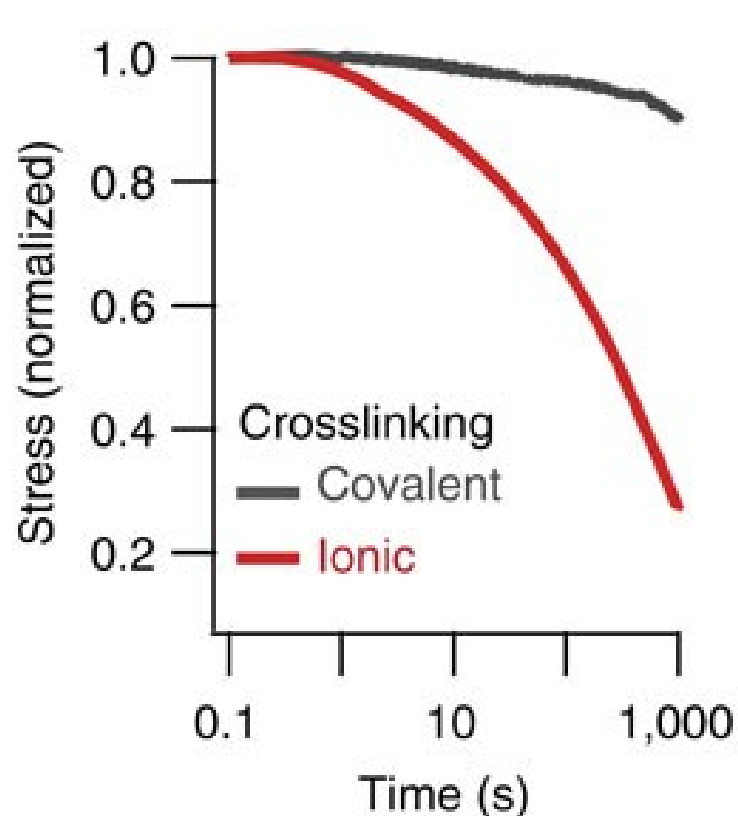
Example: Tissues



Chaudhuri et al.,
Nature 2020



Step Strain vs Oscillatory Shear

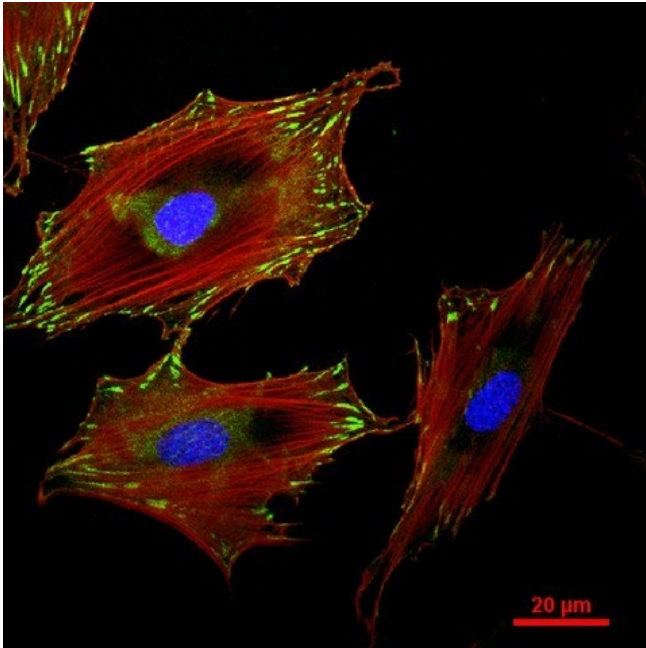


Chaudhuri et al.,
Nat Comm 2015

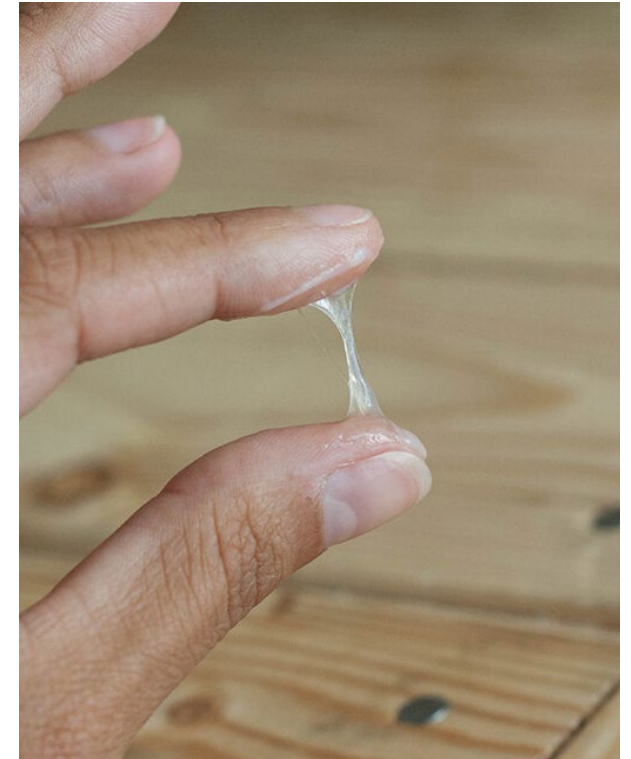
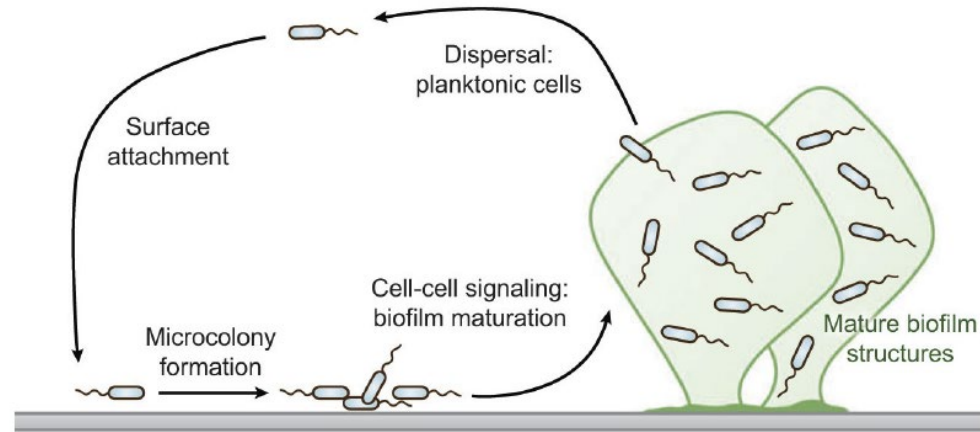
Step strain:
-> Less information, but larger window of time

Oscillatory shear
-> More information, but much slower / small window of time

Biological hydrogels are often small volume

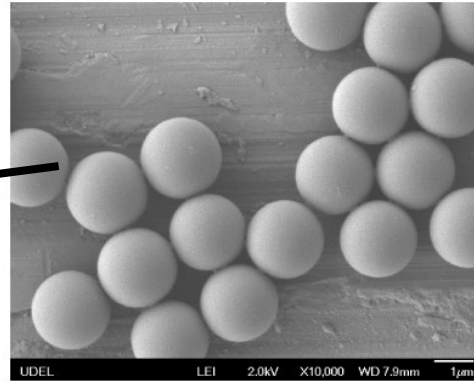
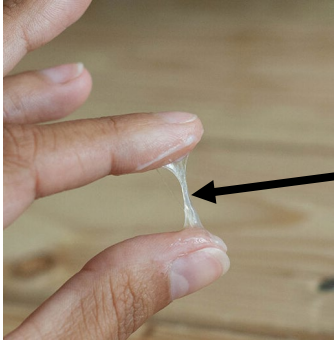


Conway institute

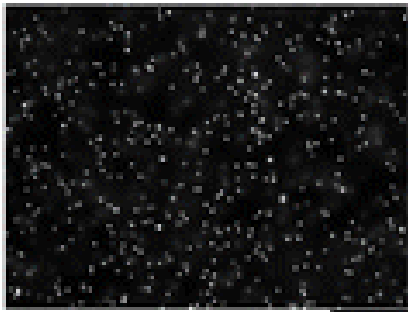


Small volumes in biological systems makes conventional rheology challenging

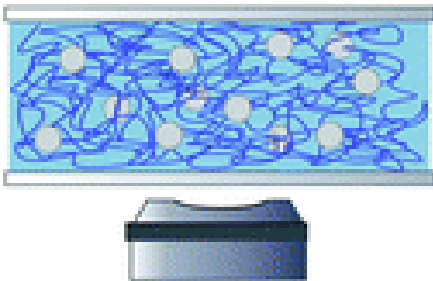
Solution: Microrheology



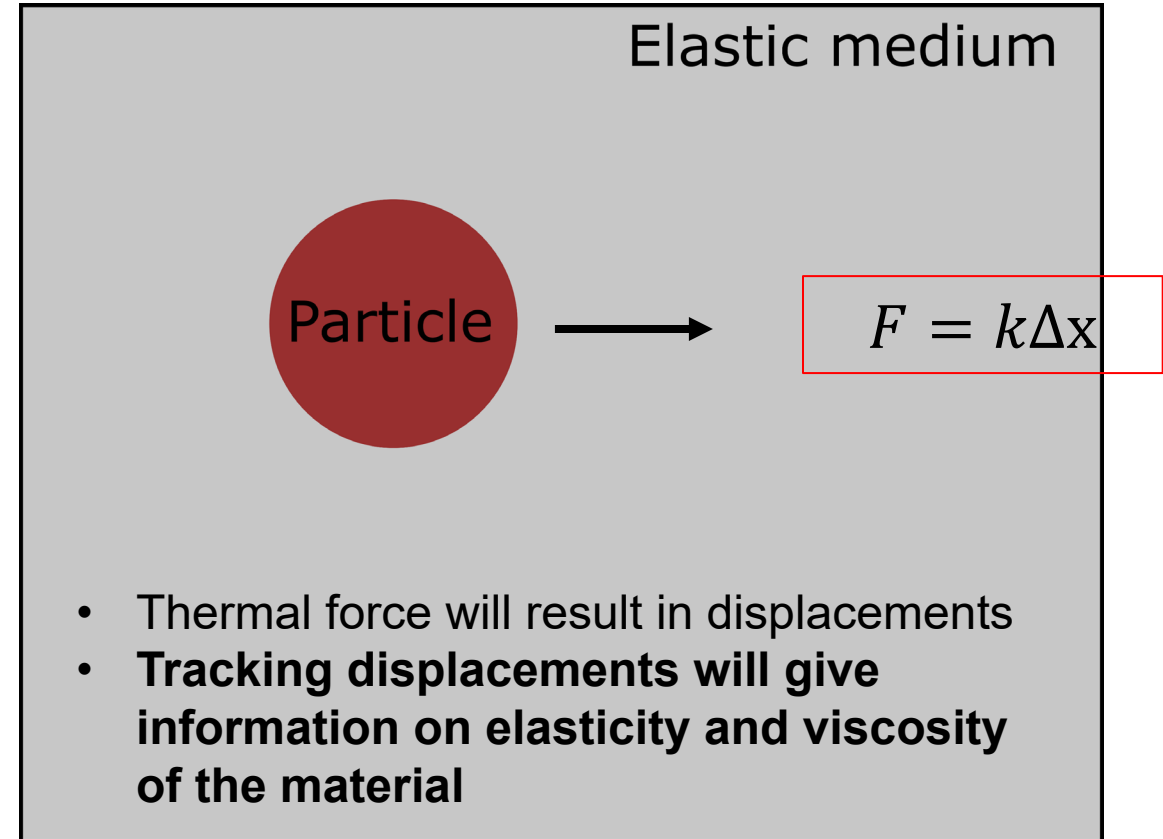
polystyrene microspheres



Observe fluctuation of (usually fluorescent) particles in hydrogel with a microscope



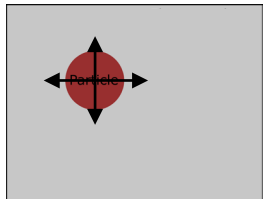
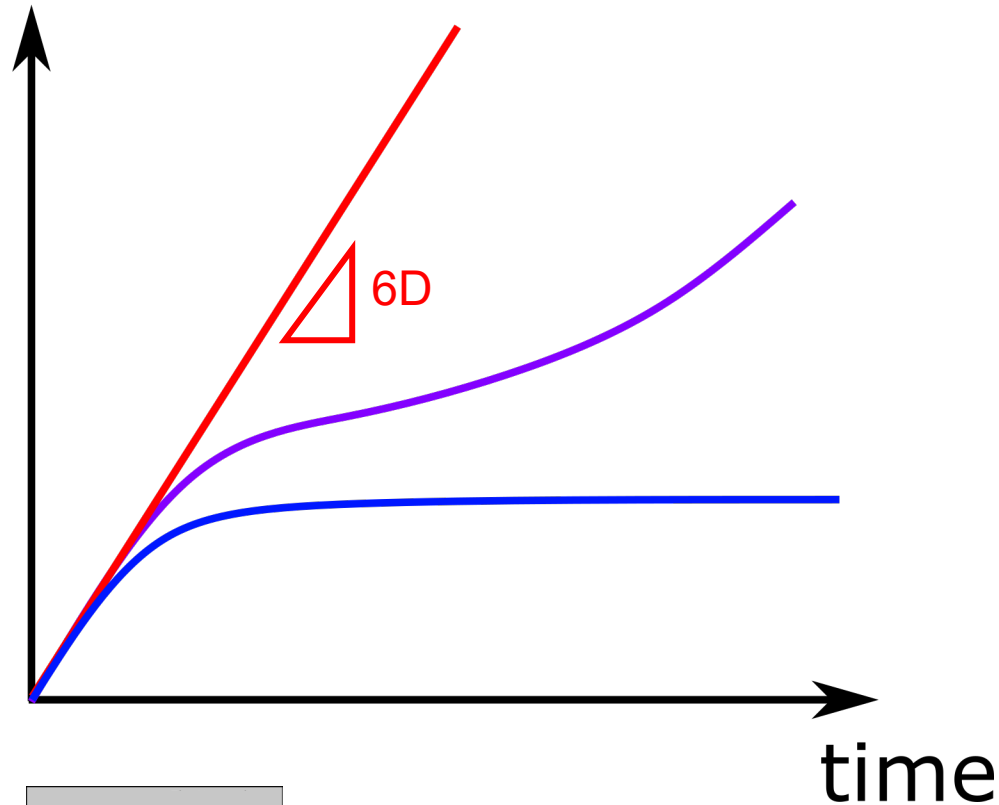
Eric Furst, SOR 2017 talk



Useful textbook: "Microrheology" by Eric Furst and Todd Squires

Microrheology

MSD



Liquid: MSD $\langle r^2(t) \rangle$ gives viscosity η

➤ Diffusivity D scales with η via the Stokes-Einstein theorem

$$D = \frac{k_B T}{6\pi\eta R}$$

Solid: MSD $\langle r^2(t) \rangle$ gives elasticity G

➤ Hooke's theorem

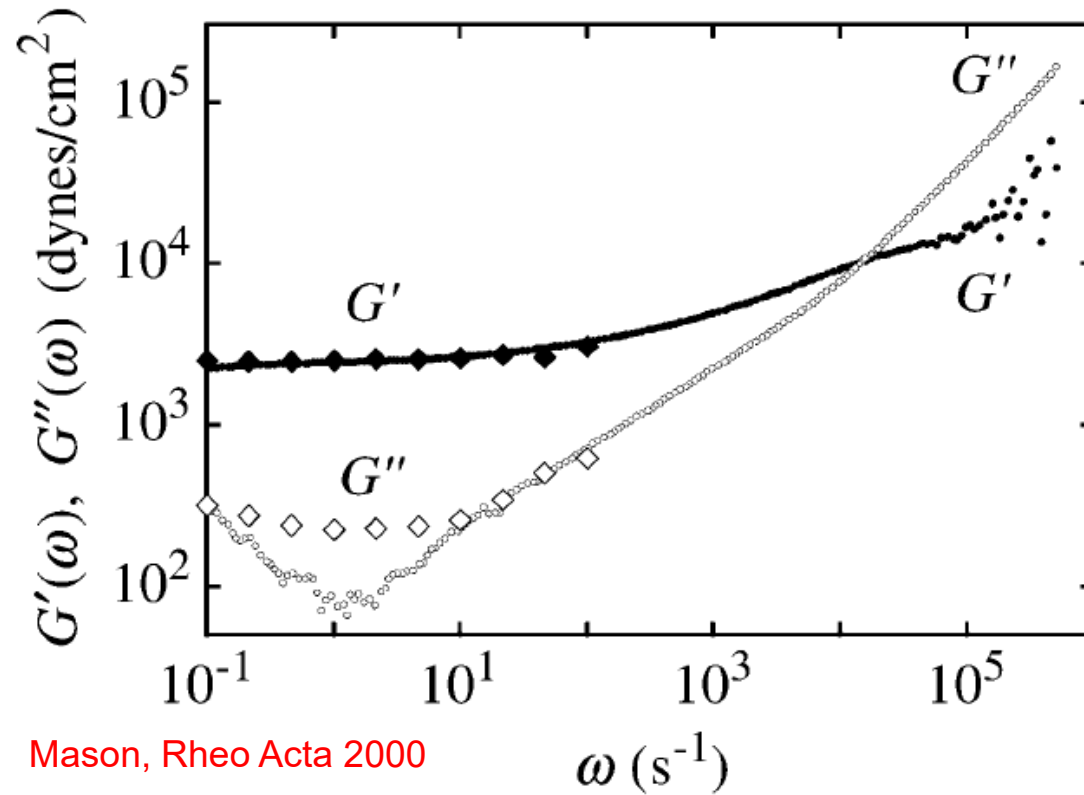
$$F = k\Delta x \Rightarrow kT = G\sqrt{\langle r^2(t) \rangle}$$

Viscoelastic: MSD interpolates between solid and liquid like response, gives $G^*(\omega)$

➤ Generalized Stokes-Einstein Theorem

$$\langle \Delta \tilde{r}^2(s) \rangle = \frac{k_B T}{\pi R s \tilde{G}^*(s)}$$

Microrheology – Example data



Mason, Rheo Acta 2000

Pros:

- Only need $< 10 \mu\text{L}$ of sample
- Can access higher frequencies
- No sample contact / deformation

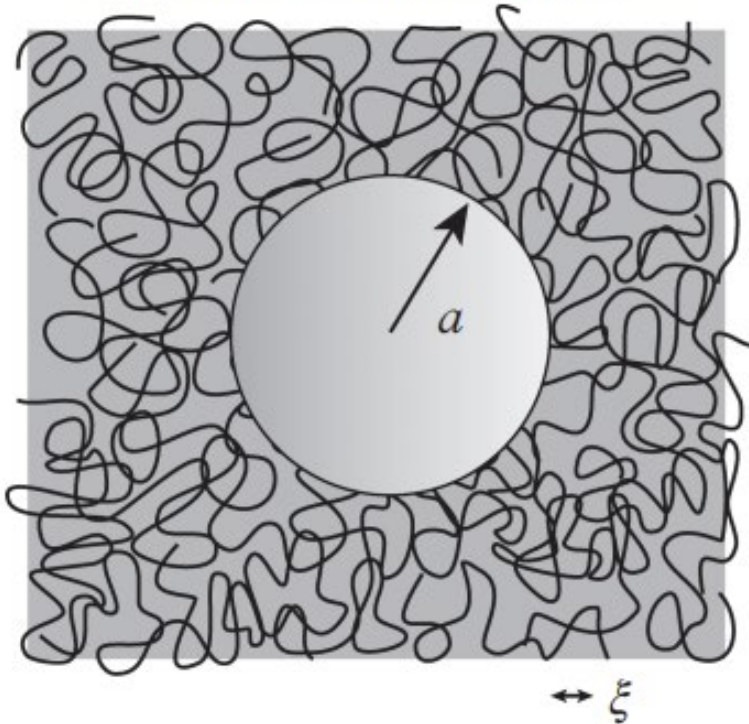
Cons:

- Complicated analysis
- Affected by structural heterogeneity
- Can't examine stiff materials

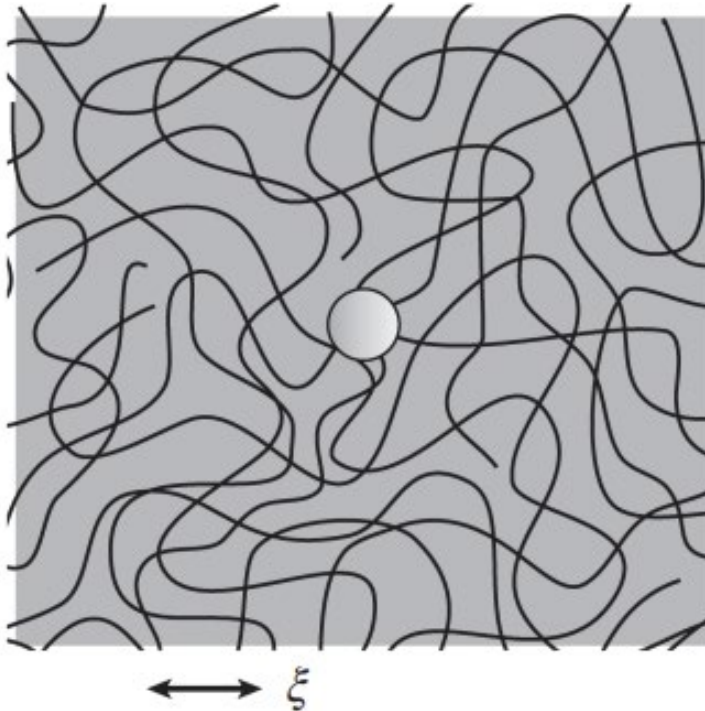
Fig. 3 The frequency-dependent storage modulus, $G'(\omega)$, (solid symbols) and loss modulus, $G''(\omega)$, (open symbols) for the concentrated emulsion obtained from $\langle \Delta r^2(t) \rangle$ in Fig. 1 using the estimates for the generalized Stokes–Einstein equation, Eqs. (10) and (11) (small circles), and by mechanical measurements (large diamonds)

Microrheology – Constraints and challenges

continuum limit satisfied



non-continuum



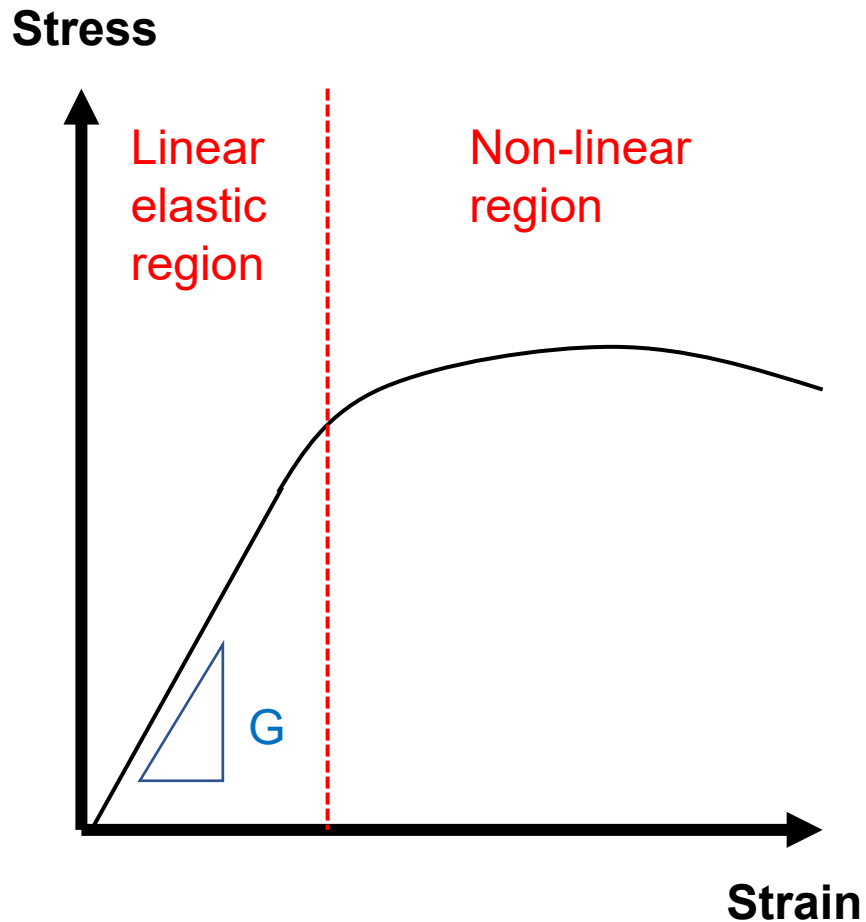
Requirement:

- 1) **Embedded particle must be bigger than the mesh size of the hydrogel***
- 2) **No particle-particle or particle-polymer interactions**

* Tracking dynamics of smaller particles can be a useful way to study mesh size

Additional readings: “Microrheology” by Eric Furst and Todd Squires
Mason and Weitz, PRL 1995
Gittes and Schnurr et al., Macromol 1997, PRL 1997
Squires and Mason, Ann Rev Fluid Mech 2010

Other forms of rheology to keep in mind



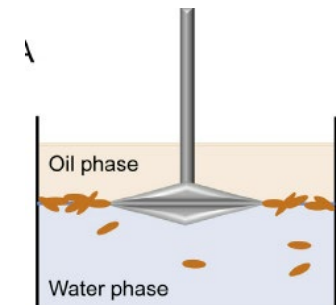
Scattering microrheology: Microrheology using light/x-ray scattering rather than microscopy – easier data analysis but requires more technical setup (see additional slides)

Dynamic mechanical analysis: Similar to rheometry but in normal direction rather than shear; more useful for stiff materials (MPa~GPa)

Interfacial rheology: Useful for measuring interface mechanics

Example: Measuring surfactant layer viscoelasticity in oil-water emulsions

Ruhs et al., *Colloids and surfaces B* 2014

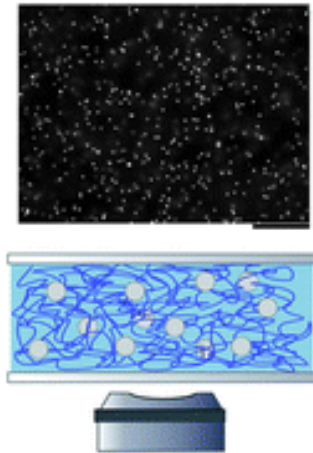


Non-linear rheology: Extensional rheology, large-amplitude oscillatory shear, steady shear, active microrheology, ...

Summary of “current” techniques

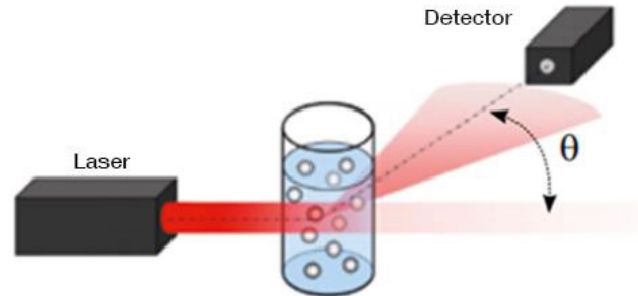
Particle tracking

- $\sim 10^2$ Pa
- ~ 1 uL vol
- Higher frequency
- **Difficult analysis**
- **Sample heterogeneity**



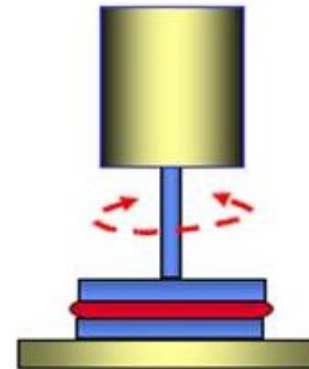
Scattering

- $\sim 10^4$ Pa
- 10~200 uL vol
- Higher frequency
- **Specialized instrument**
- **Sample heterogeneity**



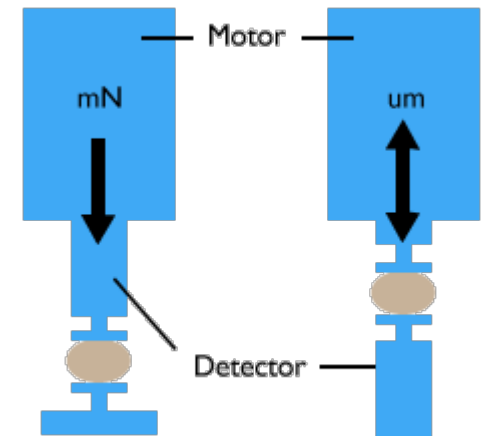
Rheometer

- $\sim 10^6$ Pa
- Established method
- Easy features like T control
- 50 ~ 500 uL vol
- **Requires mechanical deformations**



Dynamic mechanical analyzer

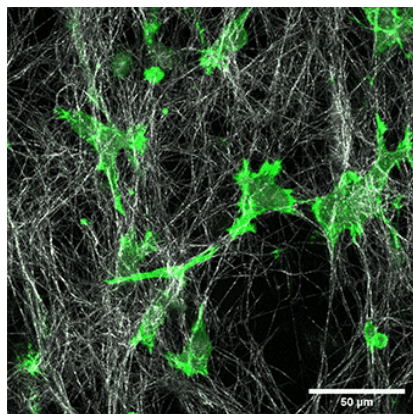
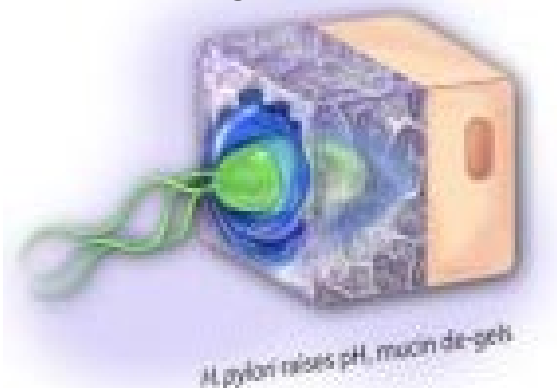
- $10^6 \sim 10^9$ Pa
- 500 ~ 5000 uL vol
- Hard samples only
- **Required mechanical deformations**



Sample volume, Modulus

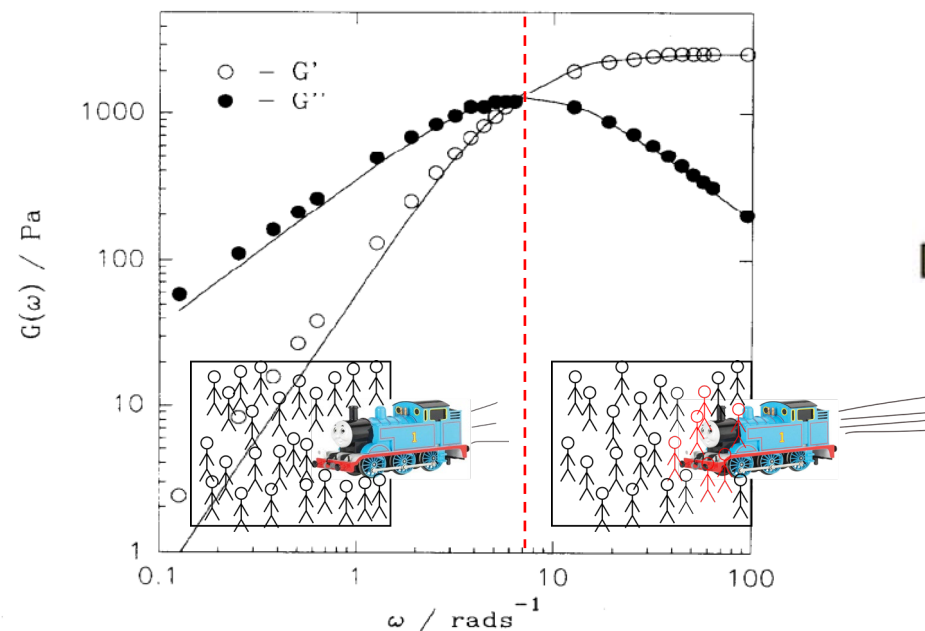
Viscoelasticity

Why should we care?
Dynamics affects crucial biological function

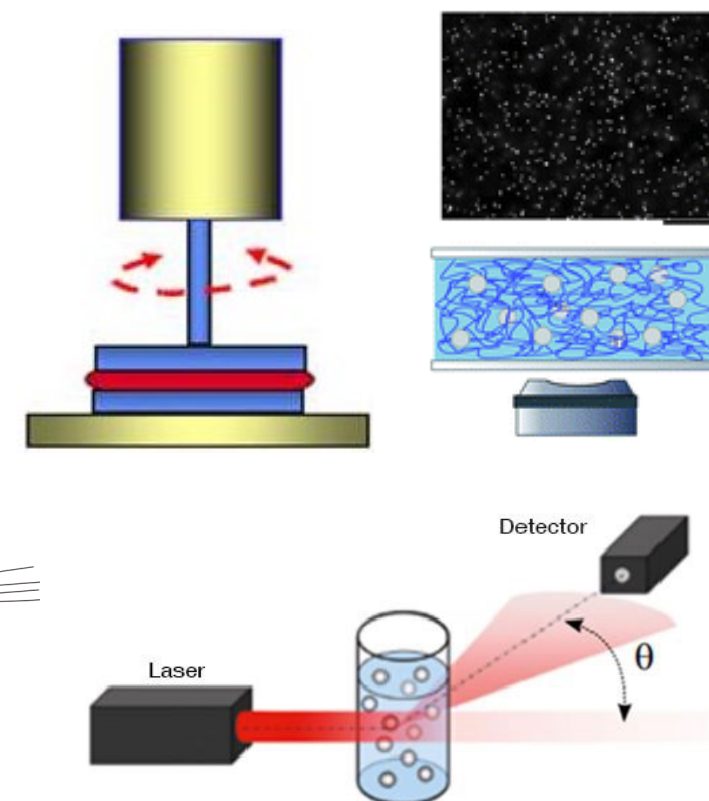


What is it?

Measure of elasticity, viscosity, and the dynamical timescale of the system



How do we measure it?
macrorheology, microrheology, ...



Additional slides

Microrheology – theoretical background

$$\eta^*(\omega) = i\omega G^*(\omega)$$

$$\mathcal{L}(V(t)) = \tilde{V}(s)$$

The Stokes-Einstein theorem:

$$D = \frac{k_B T}{\xi} = \frac{k_b T}{6\pi\eta a}$$

Einstein: Diffusivity related to hydrodynamic resistance

Stokes: Diffusivity related to viscosity

Langevin equation (variation of Newton's law of motion):

$$m \frac{dV(t)}{dt} = f_R(t) - \int_0^t \xi(t-t')V(t')dt'$$

Laplace transform -> Multiply by $V(0)$ to obtain velocity autocorrelation function (to obtain the MSD in complex space) which can be related to ξ

$$\langle V(0)\tilde{V}(s) \rangle = \frac{s^2}{2} \langle \Delta\tilde{r}^2(s) \rangle = \frac{nk_B T}{\tilde{\xi}(s)}$$

The Generalized Stokes-Einstein Relation (GSER)

$$\langle \Delta\tilde{r}^2(s) \rangle = \frac{nk_B T}{3\pi a s \tilde{G}^*(s)}$$



User-friendly adaptation

$$\tilde{G}^*(s) = \frac{nk_B T}{3\pi a \langle r^2(t) \rangle \Gamma\left(1 + \frac{d \ln \langle r^2(t) \rangle}{d \ln t}\right)}$$

$$G^*(\omega) = \mathcal{L}^{-1}(\tilde{G}^*(s))$$

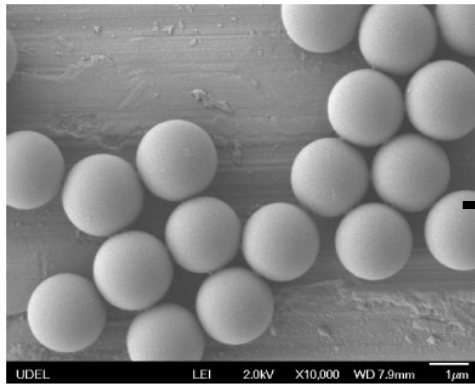
Microrheology via scattering

Idea: Instead of tracking individual particles, track the motion of ensemble of particles in reciprocal space

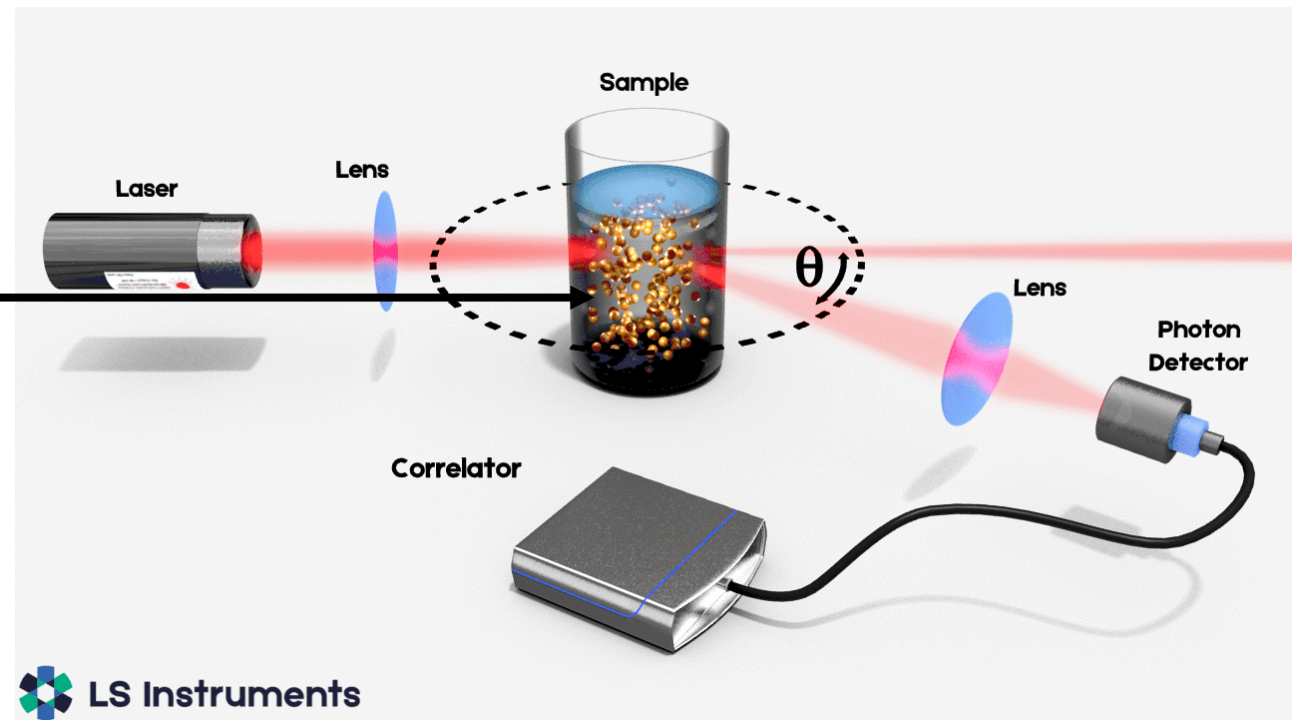
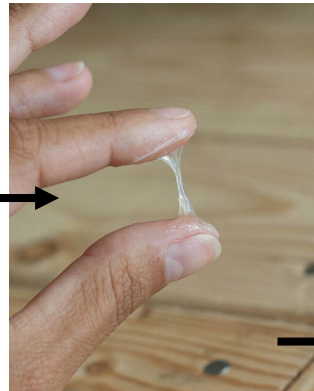
Method: Diffusing wave spectroscopy (DWS), X-ray photon correlation spectroscopy (XPCS)

Pine et al., PRL 1988

Leheny et al., Curr Op Colloid Int Sci 2012



polystyrene microspheres



Pros:

Easier data analysis

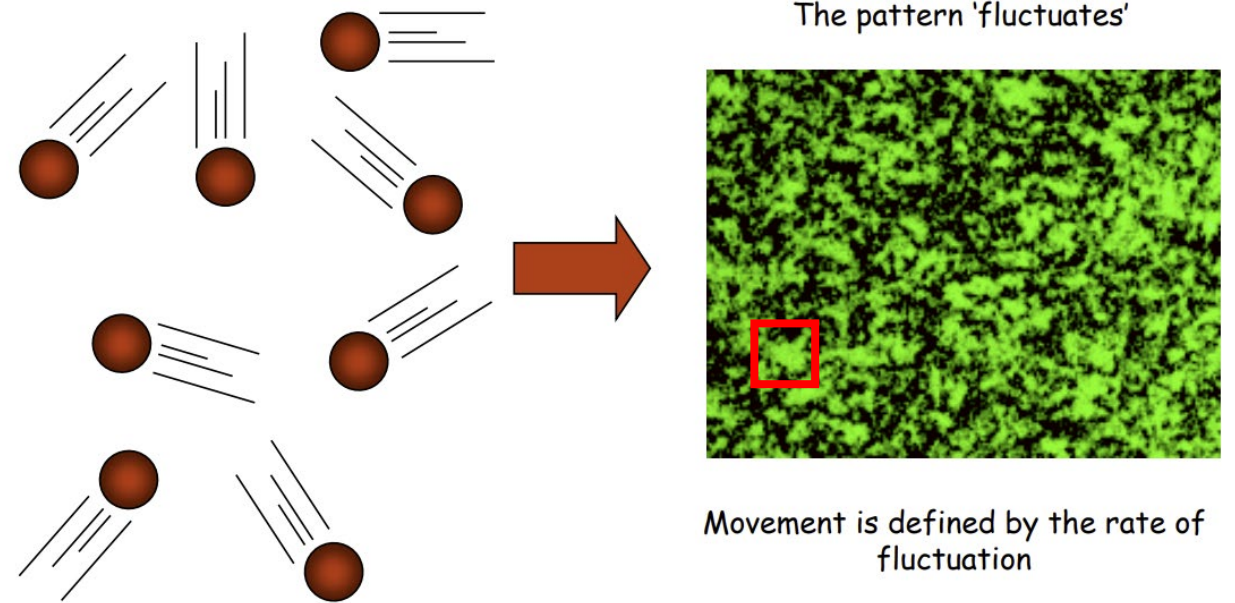
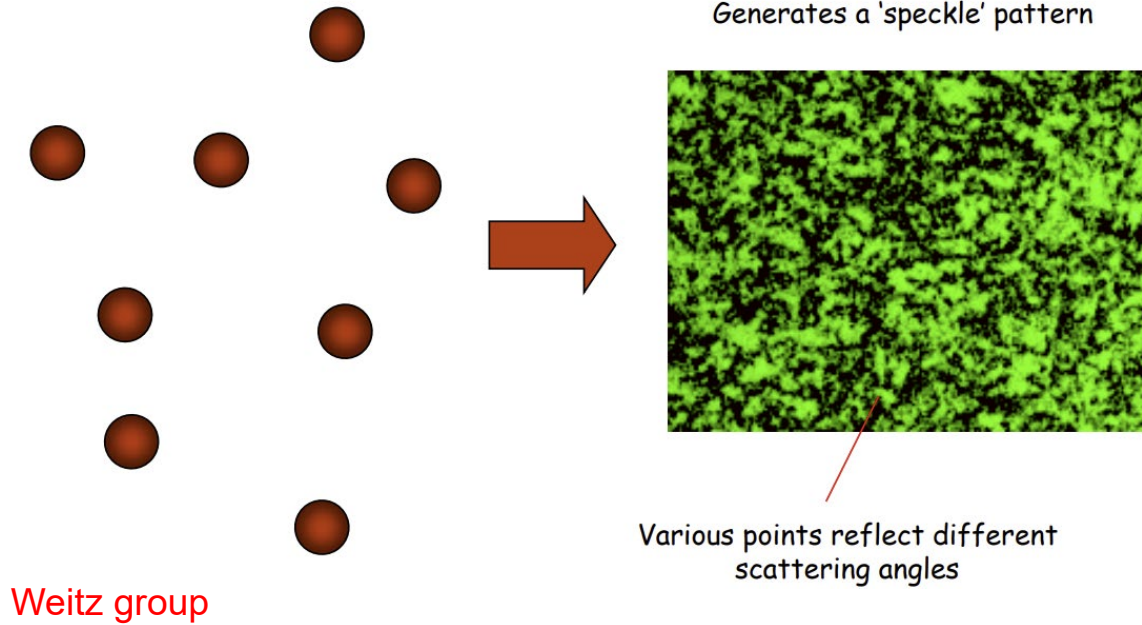
Better ensemble averaging

Can even track system without tracers

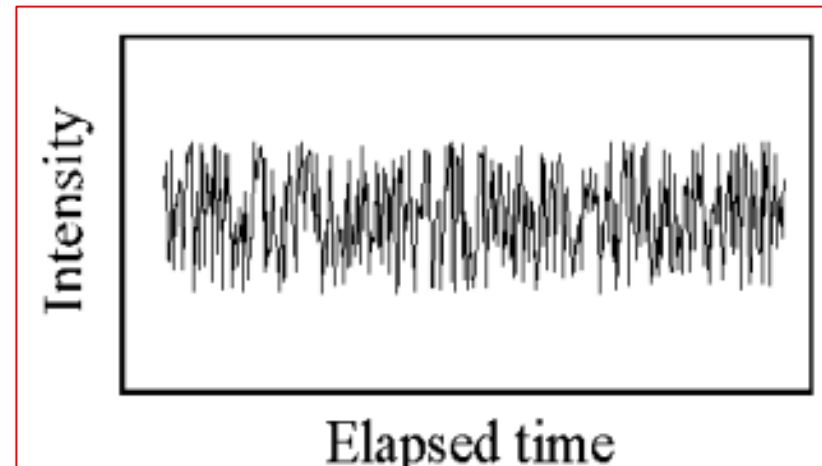
Cons:

Need specialized instruments, and either large volumes (DWS) or radiation tolerance (XPCS)

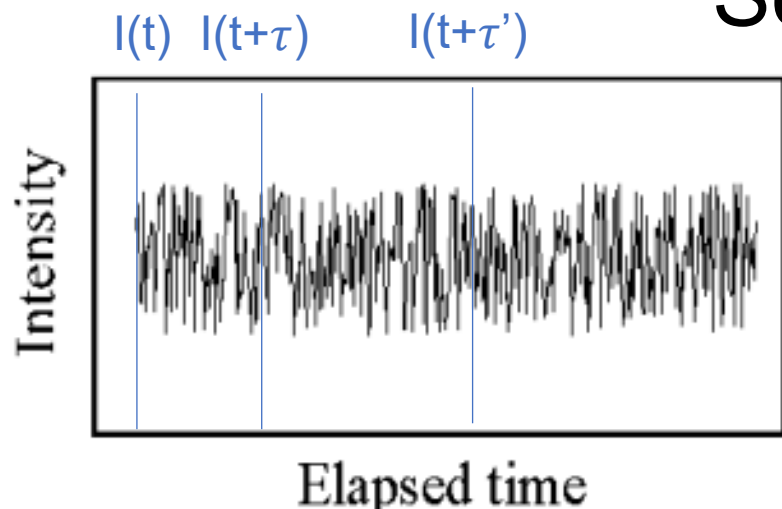
Scattering microrheology



Measure intensity fluctuation of speckles



Scattering microrheology



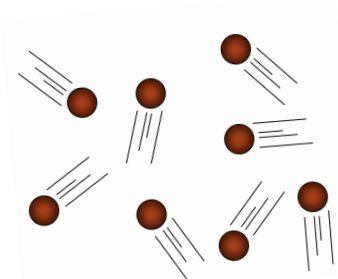
Intensity correlation function: integral of product of intensities at different delay times

$$g_2(t) = \frac{1}{t_{max}} \int_0^{t_{max}} I(t)I(t + \tau)d\tau$$

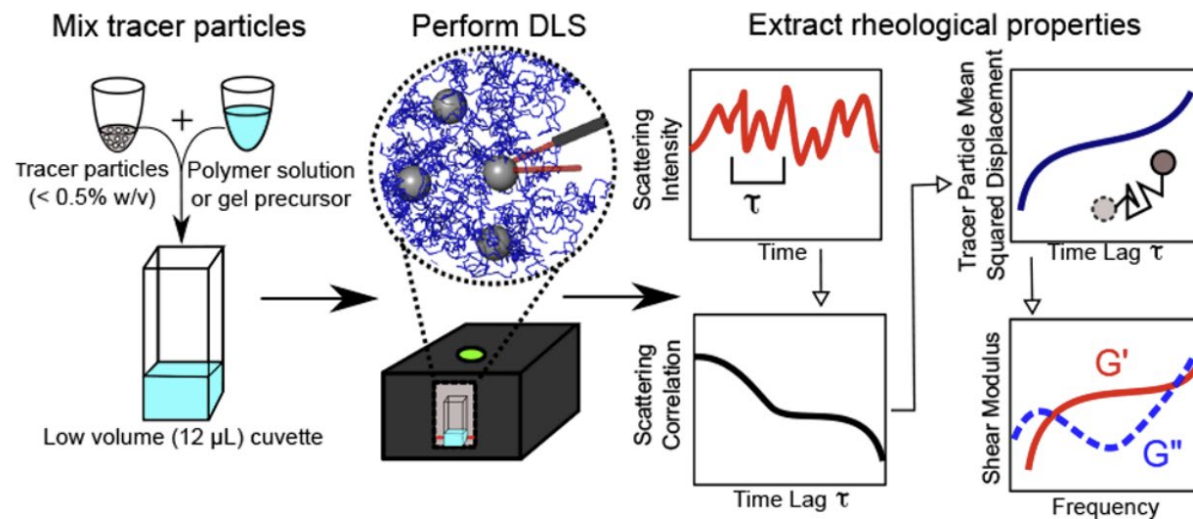
Once you have the MSD, use GSER to obtain $G^*(\omega)$

Now use Siegert relation: $g_2(\tau) = 1 + B|g_1(\tau)|^2$

Where g_1 is the field correlation (which describes correlated particle movement) and for Brownian motion follows:



$$g_1(\tau) = \exp\left(-\frac{q^2 \Delta r^2(\tau)}{6}\right)$$



Krajina et al., ACS Cent Sci 2017